# Algorithmic properties of tree-like inverse monoids

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#### Inverse monoids

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Natural partial order:  $a \le b$  iff there exists an idempotent e with a = be.

An inverse monoid presentation:  $M = Inv\langle A \mid u_i = v_i \ (i \in I) \rangle$ , where  $u_i, v_i$  are words in  $(A \cup A^{-1})^*$ — the "most general" inverse monoid generated by A, where

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The main result of the talk: inverse monoids which satisfy a certain geometric property have solvable word problem, (and other nice algorithmic properties).

# The Cayley graph

Let M be an inverse monoid generated by A.

The Cayley graph  $\Gamma(M, A)$  of M is an edge-labeled, directed graph

- with vertex set M,
- ▶ for any  $m \in M$ , and any  $a \in A \cup A^{-1}$ ,  $m \xrightarrow{a} ma$  is an edge.

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Note:

- ►  $aa^{-1}$ ,  $a^{-1}a$  are not always loops,
- the Cayley graph is not strongly connected.

## The strongly connected components

Fact: if m, ma are in the strongly connected component, then  $maa^{-1} = m$ , that is, in these components, edges occur in inverse pairs.

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#### Definition

The strongly connected component of m is called the **Schützenberger graph** of m, and is denoted by S(m).

**Fact:**  $mm^{-1}$  is always a vertex of S(m), moreover, it is the unique idempotent vertex.

## Schützenberger automata

Let  $M = \langle A \rangle$  be an inverse monoid. The Schützenberger automaton of m:  $SA(m) = (S(m), mm^{-1}, m)$ . Theorem (Stephen, 1990)

► 
$$L(\mathcal{SA}(m)) = \{w \in (A \cup A^{-1})^* : w \ge_M m\},$$

- ▶ for  $u, v \in (A \cup A^{-1})^*$ ,  $u_M = v_M$  iff  $v \in L(SA(u))$  and  $u \in L(SA(v))$ ,
- the word problem for M boils down to deciding the languages of the Schützenberger automata

# Constructing $\mathcal{SA}(w)$

Let  $M = \text{Inv}\langle A \mid u_i = v_i \ (i \in I) \rangle$ , and  $w \in (A \cup A^{-1})^*$ . To build SA(w),

- 1. start with the linear automaton corresponding to w;
- 2. **expand:** if one side of a relation is readable between two vertices and the other is not, add it to the graph;
- 3. **fold:** if  $u \xrightarrow{a} v_1$  and  $u \xrightarrow{a} v_2$ , or  $v_1 \xrightarrow{a} u$  and  $v_2 \xrightarrow{a} u$ , identify  $v_1$  and  $v_2$ ;
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#### Theorem (Stephen)

These operations are confluent, and the limit automaton is SA(w).

#### Graphs as metric spaces

Let  $\Gamma$  be a graph,  $u, v \in V(\Gamma)$ ,

 $d(u, v) := \min\{n : e_1 \dots e_n \text{ is a path from } u \text{ to } v\}.$ 

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A geodesic from u to v: a path with length d(u, v).

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## Examples

- finite inverse monoids
- ► free inverse monoids (Schützenberger graphs are finite trees)
- Inv⟨A | u<sub>i</sub> = v<sub>i</sub> (i ∈ I)⟩ where u<sub>i</sub>, v<sub>i</sub> are equal to 1 in the free group (Schützenberger graphs are trees)
- virtually free groups
- $\blacktriangleright \operatorname{Inv}\langle x_1,\ldots,x_n,y_1,\ldots,y_n \mid [x_1,y_1]\cdot\ldots\cdot [x_n,y_n] = 1 \rangle \ (n \ge 2)$

## Regular geodesics

Let  $M = \langle X \rangle$  be an inverse monoid. Geo(w) := set of labels of geodesics in S(w) from  $x_0 := ww^{-1}$ . Theorem

If M is a finitely presented tree-like inverse monoid, then Geo(w) is regular.

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#### Theorem

If M is a finitely presented tree-like inverse monoid, then Geo(w) is regular.

**Remark:** there exist f.g. tree-like inverse monoids which don't have a regular set of geodesics, and hence are not finitely presented.

## The main theorems

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#### Theorem

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Moreover, there is an algorithm that constructs the pushdown automata with input the presentation and w. Hence:

#### Theorem

The word problem for tree-like inverse monoids is uniformly decidable, that is, there is a Turing machine with input

• 
$$M = \text{Inv}\langle A \mid u_i = v_i \ (1 \le i \le n) \rangle$$

► 
$$u, v \in (A \cup A^{-1})^*$$

that halts if and only if M is tree-like, and then decides if  $u =_M v$ .

# Thank you for your attention!