 Free-abelian-by-free groups 	Stallings' automata	Vectored Stallings' automata	Membership	Intersection

The intersection problem in $F_n \times \mathbb{Z}^m$

Enric Ventura

Departament de Matemàtiques Universitat Politècnica de Catalunya

SandGAL2019 Semigroups and Groups, Automata, Logics

June 12th, 2019,

(joint with J. Delgado)

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection
A				

Outline

- Free-abelian-by-free groups
- 2 Stallings' automata
- Vectored Stallings' automata
- 4 Membership





 Free-abelian-by-free groups 	Stallings' automata	Vectored Stallings' automata	Membership	Intersection

Outline



- 2 Stallings' automata
- Vectored Stallings' automata
- 4 Membership



Vectored Stallings' automata

Membership 00

・ コット (雪) (小田) (コット 日)

Finitely generated free-abelian groups

This talk is about semidirect products of f.g. free-abelian groups by f.g. free groups (free-abelian-by-free, for short).

For all the talk, • elements from \mathbb{Z}^m are row integral vectors of length *m*, with additive notation;

• think endomorphisms of \mathbb{Z}^m as $m \times m$ integral matrices **A**, acting on the right $\mathbf{u} \mapsto \mathbf{u}\mathbf{A}$;

• Aut $(\mathbb{Z}^m) = \operatorname{GL}_m(\mathbb{Z})$ is the group of invertible matrices.

Vectored Stallings' automata

Membership 00

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

Finitely generated free-abelian groups

This talk is about semidirect products of f.g. free-abelian groups by f.g. free groups (free-abelian-by-free, for short).

For all the talk,

• elements from \mathbb{Z}^m are row integral vectors of length *m*, with additive notation;

• think endomorphisms of \mathbb{Z}^m as $m \times m$ integral matrices **A**, acting on the right $\mathbf{u} \mapsto \mathbf{u}\mathbf{A}$;

• $\operatorname{Aut}(\mathbb{Z}^m) = \operatorname{GL}_m(\mathbb{Z})$ is the group of invertible matrices.

Vectored Stallings' automata

Membership 00

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

Finitely generated free-abelian groups

This talk is about semidirect products of f.g. free-abelian groups by f.g. free groups (free-abelian-by-free, for short).

For all the talk,

• elements from \mathbb{Z}^m are row integral vectors of length *m*, with additive notation;

• think endomorphisms of \mathbb{Z}^m as $m \times m$ integral matrices **A**, acting on the right $\mathbf{u} \mapsto \mathbf{u}\mathbf{A}$;

• $\operatorname{Aut}(\mathbb{Z}^m) = \operatorname{GL}_m(\mathbb{Z})$ is the group of invertible matrices.

Vectored Stallings' automata

Membership 00

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

Finitely generated free-abelian groups

This talk is about semidirect products of f.g. free-abelian groups by f.g. free groups (free-abelian-by-free, for short).

For all the talk,

• elements from \mathbb{Z}^m are row integral vectors of length *m*, with additive notation;

• think endomorphisms of \mathbb{Z}^m as $m \times m$ integral matrices **A**, acting on the right $\mathbf{u} \mapsto \mathbf{u}\mathbf{A}$;

• $\operatorname{Aut}(\mathbb{Z}^m) = \operatorname{GL}_m(\mathbb{Z})$ is the group of invertible matrices.

Vectored Stallings' automata

Membership 00

Abelian-by-free groups

- Let $X = \{x_1, \ldots, x_n\}$ be a set, and \mathbb{F}_X the free group on it;
- fix matrices $\mathbf{A}_j \in GL_m(\mathbb{Z})$, j = 1, ..., n and consider the action $\mathbf{A}_{\bullet} : \mathbb{F}_X \to Aut(\mathbb{Z}^m)$, $x_j \mapsto A_j$;
- consider the corresponding semidirect product $\mathbb{G}_{\mathbf{A}} = \mathbb{F}_n \ltimes_{\mathbf{A}_{\bullet}} \mathbb{Z}^m$,

$$\mathbb{G}_{\mathbf{A}} = \left\langle \begin{array}{cc} x_1, \dots, x_n \\ t_1, \dots, t_m \end{array} \middle| \begin{array}{cc} t_i t_k = t_k t_i & \forall i, k \in [1, m] \\ x_j^{-1} t_i x_j = t^{\mathbf{e}_i \mathbf{A}_j} & \forall i \in [1, m], \forall j \in [1, n] \end{array} \right\rangle$$

- Notation: $t^{u} := t^{(u_1, ..., u_m)} := t_1^{u_1} t_2^{u_2} \cdots t_m^{u_m}$, where 't' is meaningless;
- This way, we get multiplicative notation, $t^{u}t^{v} = t^{u+v}$.

Of course, the case of trivial action, $\mathbf{A}_j = \mathbf{I}_m$, corresponds to the direct product $\mathbb{F}_X \times \mathbb{Z}^m$, where the x_i 's commute with the t_i 's.

くりょう 小田 マイビット 日 うくの

1. Free-abelian-by-free groups ○○●○○○	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection
Abelian-by-f	ree groups			

- Let $X = \{x_1, ..., x_n\}$ be a set, and \mathbb{F}_X the free group on it;
- fix matrices $\mathbf{A}_j \in GL_m(\mathbb{Z})$, j = 1, ..., n and consider the action $\mathbf{A}_{\bullet} : \mathbb{F}_X \to Aut(\mathbb{Z}^m)$, $x_j \mapsto A_j$;

• consider the corresponding semidirect product $\mathbb{G}_{A} = \mathbb{F}_{n} \ltimes_{A_{\bullet}} \mathbb{Z}^{m}$,

$$\mathbb{G}_{\mathbf{A}} = \left\langle \begin{array}{cc} x_1, \dots, x_n \\ t_1, \dots, t_m \end{array} \middle| \begin{array}{cc} t_i t_k = t_k t_i & \forall i, k \in [1, m] \\ x_j^{-1} t_i x_j = t^{\mathbf{e}_i \mathbf{A}_j} & \forall i \in [1, m], \forall j \in [1, n] \end{array} \right\rangle$$

• Notation: $t^{u} := t^{(u_1, ..., u_m)} := t_1^{u_1} t_2^{u_2} \cdots t_m^{u_m}$, where 't' is meaningless;

• This way, we get multiplicative notation, $t^{u}t^{v} = t^{u+v}$.

1. Free-abelian-by-free groups ○○●○○○	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection
Abelian-by-f	ree groups			

- Let $X = \{x_1, \ldots, x_n\}$ be a set, and \mathbb{F}_X the free group on it;
- fix matrices $\mathbf{A}_j \in GL_m(\mathbb{Z})$, j = 1, ..., n and consider the action $\mathbf{A}_{\bullet} : \mathbb{F}_X \to Aut(\mathbb{Z}^m)$, $x_j \mapsto A_j$;
- consider the corresponding semidirect product $\mathbb{G}_{\mathbf{A}} = \mathbb{F}_n \ltimes_{\mathbf{A}_{\bullet}} \mathbb{Z}^m$,

$$\mathbb{G}_{\mathbf{A}} = \left\langle \begin{array}{cc} x_1, \dots, x_n \\ t_1, \dots, t_m \end{array} \middle| \begin{array}{cc} t_i t_k = t_k t_i & \forall i, k \in [1, m] \\ x_j^{-1} t_i x_j = t^{\mathbf{e}_i \mathbf{A}_j} & \forall i \in [1, m], \forall j \in [1, n] \end{array} \right\rangle$$

• Notation: $t^{\mathbf{u}} := t^{(u_1, \dots, u_m)} := t_1^{u_1} t_2^{u_2} \cdots t_m^{u_m}$, where 't' is meaningless;

• This way, we get multiplicative notation, $t^{u}t^{v} = t^{u+v}$.

1. Free-abelian-by-free groups ○○●○○○	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection
Abelian-by-f	ree groups			

- Let $X = \{x_1, \ldots, x_n\}$ be a set, and \mathbb{F}_X the free group on it;
- fix matrices $\mathbf{A}_j \in GL_m(\mathbb{Z})$, j = 1, ..., n and consider the action $\mathbf{A}_{\bullet} : \mathbb{F}_X \to Aut(\mathbb{Z}^m)$, $x_j \mapsto A_j$;
- consider the corresponding semidirect product $\mathbb{G}_{\mathbf{A}} = \mathbb{F}_n \ltimes_{\mathbf{A}_{\bullet}} \mathbb{Z}^m$,

$$\mathbb{G}_{\mathbf{A}} = \left\langle \begin{array}{cc} x_1, \dots, x_n \\ t_1, \dots, t_m \end{array} \middle| \begin{array}{cc} t_i t_k = t_k t_i & \forall i, k \in [1, m] \\ x_j^{-1} t_i x_j = t^{\mathbf{e}_i \mathbf{A}_j} & \forall i \in [1, m], \forall j \in [1, n] \end{array} \right\rangle$$

• Notation: $t^{u} := t^{(u_1, ..., u_m)} := t_1^{u_1} t_2^{u_2} \cdots t_m^{u_m}$, where 't' is meaningless;

• This way, we get multiplicative notation, $t^{u}t^{v} = t^{u+v}$.

1. Free-abelian-by-free groups ○○●○○○	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection
Abelian-by-f	ree groups			

- Let $X = \{x_1, \ldots, x_n\}$ be a set, and \mathbb{F}_X the free group on it;
- fix matrices $\mathbf{A}_j \in GL_m(\mathbb{Z})$, j = 1, ..., n and consider the action $\mathbf{A}_{\bullet} : \mathbb{F}_X \to Aut(\mathbb{Z}^m)$, $x_j \mapsto A_j$;
- consider the corresponding semidirect product $\mathbb{G}_{\mathbf{A}} = \mathbb{F}_n \ltimes_{\mathbf{A}_{\bullet}} \mathbb{Z}^m$,

$$\mathbb{G}_{\mathbf{A}} = \left\langle \begin{array}{cc} \mathbf{x}_1, \dots, \mathbf{x}_n \\ t_1, \dots, t_m \end{array} \middle| \begin{array}{cc} t_i t_k = t_k t_i & \forall i, k \in [1, m] \\ \mathbf{x}_j^{-1} t_i \mathbf{x}_j = t^{\mathbf{e}_i \mathbf{A}_j} & \forall i \in [1, m], \forall j \in [1, n] \end{array} \right\rangle$$

- Notation: $t^{\mathbf{u}} := t^{(u_1, \ldots, u_m)} := t_1^{u_1} t_2^{u_2} \cdots t_m^{u_m}$, where 't' is meaningless;
- This way, we get multiplicative notation, $t^{u}t^{v} = t^{u+v}$.

1. Free-abelian-by-free groups ○○●○○○	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection
Abelian-by-f	ree groups			

- Let $X = \{x_1, \ldots, x_n\}$ be a set, and \mathbb{F}_X the free group on it;
- fix matrices $\mathbf{A}_j \in GL_m(\mathbb{Z})$, j = 1, ..., n and consider the action $\mathbf{A}_{\bullet} : \mathbb{F}_X \to Aut(\mathbb{Z}^m)$, $x_j \mapsto A_j$;
- consider the corresponding semidirect product $\mathbb{G}_{\mathbf{A}} = \mathbb{F}_n \ltimes_{\mathbf{A}_{\bullet}} \mathbb{Z}^m$,

$$\mathbb{G}_{\mathbf{A}} = \left\langle \begin{array}{cc} x_1, \dots, x_n \\ t_1, \dots, t_m \end{array} \middle| \begin{array}{cc} t_i t_k = t_k t_i & \forall i, k \in [1, m] \\ x_j^{-1} t_i x_j = t^{\mathbf{e}_i \mathbf{A}_j} & \forall i \in [1, m], \forall j \in [1, n] \end{array} \right\rangle$$

- Notation: $t^{\mathbf{u}} := t^{(u_1, \ldots, u_m)} := t_1^{u_1} t_2^{u_2} \cdots t_m^{u_m}$, where 't' is meaningless;
- This way, we get multiplicative notation, $t^{u}t^{v} = t^{u+v}$.

Stallings' automata

Vectored Stallings' automata

Membership 00

Abelian-by-free groups

Observation

We have the standard split short exact sequence,

$$1 \longrightarrow \mathbb{Z}^m \longrightarrow \mathbb{G}_{\mathbf{A}} = \mathbb{F}_X \ltimes_{\mathbf{A}_{\bullet}} \mathbb{Z}^m \xrightarrow{\pi} \mathbb{F}_X \longrightarrow 1.$$

Observation

Writting the semidirect relation as $t^{\mathbf{u}}x_j = x_jt^{\mathbf{u}\mathbf{A}_j}$ or $t^{\mathbf{u}}x_j^{-1} = x_j^{-1}t^{\mathbf{u}\mathbf{A}_j^{-1}}$, we get normal forms for elements $g \in \mathbb{G}_{\mathbf{A}}$ as

$$g = wt^{\mathbf{u}} = w \cdot t_1^{u_1} t_2^{u_2} \cdots t_m^{u_m},$$

where $w = g\pi \in \mathbb{F}_X$ and $\mathbf{u} = (u_1, u_2, \dots, u_m) \in \mathbb{Z}^m$.

◆□▶ ◆□▶ ◆豆▶ ◆豆▶ □ のへで

Stallings' automata

Vectored Stallings' automata

Membership 00

Abelian-by-free groups

Observation

We have the standard split short exact sequence,

$$1 \longrightarrow \mathbb{Z}^m \longrightarrow \mathbb{G}_{\mathbf{A}} = \mathbb{F}_X \ltimes_{\mathbf{A}_{\bullet}} \mathbb{Z}^m \xrightarrow{\pi} \mathbb{F}_X \longrightarrow 1.$$

Observation

Writting the semidirect relation as $t^{\mathbf{u}}x_j = x_jt^{\mathbf{u}\mathbf{A}_j}$ or $t^{\mathbf{u}}x_j^{-1} = x_j^{-1}t^{\mathbf{u}\mathbf{A}_j^{-1}}$, we get normal forms for elements $g \in \mathbb{G}_{\mathbf{A}}$ as

$$g = wt^{\mathbf{u}} = w \cdot t_1^{u_1} t_2^{u_2} \cdots t_m^{u_m},$$

where $w = g\pi \in \mathbb{F}_X$ and $\mathbf{u} = (u_1, u_2, \dots, u_m) \in \mathbb{Z}^m$.

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ● ● ●

Stallings' automata

Vectored Stallings' automata

Membership

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

Subgroups of free-abelian-by-free groups

Proposition

Let $\mathbb{G}_{\mathbf{A}} = \mathbb{F}_X \ltimes_{\mathbf{A}_{\bullet}} \mathbb{Z}^m$. Then, any subgroup $H \leq \mathbb{G}_{\mathbf{A}}$ admits the decomposition $H \simeq H\pi \ltimes L_H$, where $H\pi \leq \mathbb{F}_X$, $L_H = H \cap \mathbb{Z}^m \leq \mathbb{Z}^m$, and the action is the restriction of \mathbf{A}_{\bullet} to both $H\pi$ and L_H , *i.e.*, $H\pi \to \operatorname{Aut}(L_H)$, $w \mapsto \mathbf{A}_{w|L_H}$.

Corollary

Any subgroup H of a free-abelian-by-free group $\mathbb{G}_{\mathbf{A}}$ is again free-abelian-by-free. Moreover, H is finitely generated if and only if $H\pi$ is finitely generated.

Stallings' automata

Vectored Stallings' automata

Membership

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

Subgroups of free-abelian-by-free groups

Proposition

Let $\mathbb{G}_{\mathbf{A}} = \mathbb{F}_X \ltimes_{\mathbf{A}_{\bullet}} \mathbb{Z}^m$. Then, any subgroup $H \leq \mathbb{G}_{\mathbf{A}}$ admits the decomposition $H \simeq H\pi \ltimes L_H$, where $H\pi \leq \mathbb{F}_X$, $L_H = H \cap \mathbb{Z}^m \leq \mathbb{Z}^m$, and the action is the restriction of \mathbf{A}_{\bullet} to both $H\pi$ and L_H , i.e., $H\pi \to \operatorname{Aut}(L_H)$, $w \mapsto \mathbf{A}_{w|L_H}$.

Corollary

Any subgroup H of a free-abelian-by-free group $\mathbb{G}_{\mathbf{A}}$ is again free-abelian-by-free. Moreover, H is finitely generated if and only if $H\pi$ is finitely generated.

1. Free-abelian-by-free groups ○○○○○●	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection
Goal of the t	alk			

$$\begin{array}{rcl} \{ \textit{Subgroups of } \mathbb{F}_X \} & \longleftrightarrow & \{ \textit{Stallings X-automata} \} \\ & H & \mapsto & \Gamma(H) \\ & \mathcal{L}(\mathcal{A}) & \leftarrow & \mathcal{A} \end{array}$$

to subgroups of \mathbb{G}_A , and use it to solve several algorithmic problems in free-abelian-by-free groups. We shall focus on:

• the membership problem; \checkmark

• the subgroup conjugacy problem; caution! there are $F_{14} \ltimes \mathbb{Z}^4$ groups with unsolvable CP

• the intersection problem; caution! $F_2 \times \mathbb{Z}$ is NOT Howson

1. Free-abelian-by-free groups ○0000●	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection
Goal of the t	alk			

$$\begin{array}{rcl} \{ \textit{Subgroups of } \mathbb{F}_X \} & \longleftrightarrow & \{ \textit{Stallings X-automata} \} \\ & H & \mapsto & \Gamma(H) \\ & \mathcal{L}(\mathcal{A}) & \leftarrow & \mathcal{A} \end{array}$$

to subgroups of \mathbb{G}_A , and use it to solve several algorithmic problems in free-abelian-by-free groups. We shall focus on:

- the membership problem;
- the subgroup conjugacy problem; caution! there are $F_{14}\ltimes \mathbb{Z}^4$ groups with unsolvable CP
- the intersection problem; caution! $F_2 \times \mathbb{Z}$ is NOT Howson

1. Free-abelian-by-free groups ○0000●	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection
Goal of the t	alk			

$$\begin{array}{rcl} \{ \textit{Subgroups of } \mathbb{F}_X \} & \longleftrightarrow & \{ \textit{Stallings X-automata} \} \\ & H & \mapsto & \Gamma(H) \\ & \mathcal{L}(\mathcal{A}) & \leftarrow & \mathcal{A} \end{array}$$

to subgroups of \mathbb{G}_A , and use it to solve several algorithmic problems in free-abelian-by-free groups. We shall focus on:

- the membership problem;
 ✓
- the subgroup conjugacy problem; caution! there are $F_{14}\ltimes \mathbb{Z}^4$ groups with unsolvable CP
- the intersection problem; caution! $F_2 \times \mathbb{Z}$ is NOT Howson

1. Free-abelian-by-free groups ○0000●	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection
Goal of the t	alk			

$$\begin{array}{rcl} \{ \textit{Subgroups of } \mathbb{F}_X \} & \longleftrightarrow & \{ \textit{Stallings X-automata} \} \\ & H & \mapsto & \Gamma(H) \\ & L(\mathcal{A}) & \leftarrow & \mathcal{A} \end{array}$$

to subgroups of \mathbb{G}_A , and use it to solve several algorithmic problems in free-abelian-by-free groups. We shall focus on:

- the membership problem;
 ✓
- the subgroup conjugacy problem; caution! there are $F_{14} \ltimes \mathbb{Z}^4$ groups with unsolvable CP

• the intersection problem; caution! $F_2 \times \mathbb{Z}$ is NOT Howson

1. Free-abelian-by-free groups ○0000●	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection		
Goal of the talk						

$$\begin{array}{rcl} \{ \textit{Subgroups of } \mathbb{F}_X \} & \longleftrightarrow & \{ \textit{Stallings X-automata} \} \\ & H & \mapsto & \Gamma(H) \\ & \mathcal{L}(\mathcal{A}) & \leftarrow & \mathcal{A} \end{array}$$

to subgroups of \mathbb{G}_A , and use it to solve several algorithmic problems in free-abelian-by-free groups. We shall focus on:

- the membership problem;
 ✓
- the subgroup conjugacy problem; caution! there are $F_{14}\ltimes\mathbb{Z}^4$ groups with unsolvable CP

• the intersection problem; caution! $F_2 \times \mathbb{Z}$ is NOT Howson

1. Free-abelian-by-free groups ○0000●	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection		
Goal of the talk						

$$\begin{array}{rcl} \{ \textit{Subgroups of } \mathbb{F}_X \} & \longleftrightarrow & \{ \textit{Stallings X-automata} \} \\ & H & \mapsto & \Gamma(H) \\ & L(\mathcal{A}) & \leftarrow & \mathcal{A} \end{array}$$

to subgroups of \mathbb{G}_A , and use it to solve several algorithmic problems in free-abelian-by-free groups. We shall focus on:

- the membership problem;
 ✓
- \bullet the subgroup conjugacy problem; caution! there are $F_{14}\ltimes\mathbb{Z}^4$ groups with unsolvable CP
- the intersection problem; caution! $F_2 \times \mathbb{Z}$ is NOT Howson

1. Free-abelian-by-free groups ○0000●	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection		
Goal of the talk						

$$\begin{array}{rcl} \{ \textit{Subgroups of } \mathbb{F}_X \} & \longleftrightarrow & \{ \textit{Stallings X-automata} \} \\ & H & \mapsto & \Gamma(H) \\ & \mathcal{L}(\mathcal{A}) & \leftarrow & \mathcal{A} \end{array}$$

to subgroups of \mathbb{G}_A , and use it to solve several algorithmic problems in free-abelian-by-free groups. We shall focus on:

- the membership problem;
- the subgroup conjugacy problem; caution! there are $F_{14}\ltimes \mathbb{Z}^4$ groups with unsolvable CP
- the intersection problem; caution! $F_2 \times \mathbb{Z}$ is NOT Howson

Vectored Stallings' automata

Membership 00 ntersection

Outline

- Free-abelian-by-free groups
- 2 Stallings' automata
- Vectored Stallings' automata
- Membership
- 5 Intersection

Stallings' automata

Vectored Stallings' automata

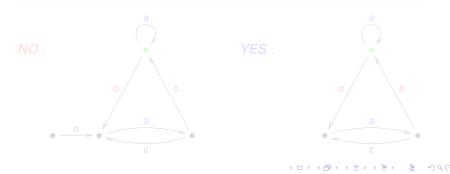
Membership

Stallings' automata

Definition

A Stallings automaton over X is a finite X-graph (V, E, q_0) , such that:

- 1- it is connected,
- 2- it is trim, (no vertex of degree 1 except possibly q_0),
- 3- it is deterministic (no two edges with the same label go out of (or into) the same vertex).



Stallings' automata

Vectored Stallings' automata

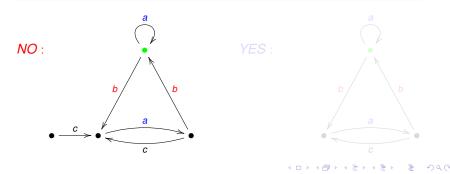
Membership 00

Stallings' automata

Definition

A Stallings automaton over X is a finite X-graph (V, E, q_0) , such that:

- 1- it is connected,
- 2- it is trim, (no vertex of degree 1 except possibly q_0),
- 3- it is deterministic (no two edges with the same label go out of (or into) the same vertex).



Stallings' automata

Vectored Stallings' automata

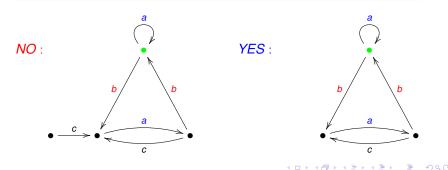
Membership 00

Stallings' automata

Definition

A Stallings automaton over X is a finite X-graph (V, E, q_0) , such that:

- 1- it is connected,
- 2- it is trim, (no vertex of degree 1 except possibly q_0),
- 3- it is deterministic (no two edges with the same label go out of (or into) the same vertex).



Vectored Stallings' automata

Membership 00

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

Stallings automata

In the influent paper

J. R. Stallings, Topology of finite graphs, Inventiones Math. 71 (1983), 551-565,

Stallings (building on previous works) gave a bijection between finitely generated subgroups of F_X and Stallings automata:

{f.g. subgroups of F_X } \longleftrightarrow {Stallings automata over X},

which is crucial for the modern understanding of the lattice of subgroups of F_X , and for many algorithmic issues about free groups.

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

Stallings automata

In the influent paper

J. R. Stallings, Topology of finite graphs, Inventiones Math. 71 (1983), 551-565,

Stallings (building on previous works) gave a bijection between finitely generated subgroups of F_X and Stallings automata:

{f.g. subgroups of F_X } \longleftrightarrow {Stallings automata over X},

which is crucial for the modern understanding of the lattice of subgroups of F_X , and for many algorithmic issues about free groups.

・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

Stallings automata

In the influent paper

J. R. Stallings, Topology of finite graphs, Inventiones Math. 71 (1983), 551-565,

Stallings (building on previous works) gave a bijection between finitely generated subgroups of F_X and Stallings automata:

{f.g. subgroups of F_X } \leftrightarrow {Stallings automata over X},

which is crucial for the modern understanding of the lattice of subgroups of F_{χ} , and for many algorithmic issues about free groups.

Stallings' automata

Vectored Stallings' automata

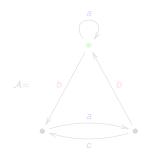
Membership

Reading the subgroup from the automata

Definition

To any given Stallings automaton $\mathcal{A} = (V, E, q_0)$, we associate its language:

 $L(A) = \{ \text{ labels of closed paths at } q_0 \} \leq F(A).$



$$(\mathcal{A}) = \{1, a, a^{-1}, bab, bc^{-1}b, babab^{-1}cb^{-1}, \ldots\}$$

 $L(\mathcal{A}) \not\ni bc^{-1}bcaa$

Vembership problem in L(A) is solvable.

▲□▶ ▲□▶ ▲三▶ ▲三▶ - 三 - のへで

Stallings' automata

Vectored Stallings' automata

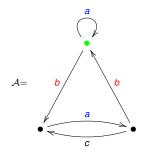
Membership

Reading the subgroup from the automata

Definition

To any given Stallings automaton $\mathcal{A} = (V, E, q_0)$, we associate its language:

 $L(A) = \{ \text{ labels of closed paths at } q_0 \} \leq F(A).$



$$(\mathcal{A}) = \{1, a, a^{-1}, bab, bc^{-1}b, babab^{-1}cb^{-1}, \ldots\}$$

 $L(\mathcal{A}) \not\ni bc^{-1}bcaa$

Membership problem in L(A) is solvable.

▲□▶ ▲□▶ ▲三▶ ▲三▶ - 三 - のへで

Stallings' automata

Vectored Stallings' automata

Membership 00

A basis for L(A)

Proposition

For every Stallings automaton $A = (V, E, q_0)$, and every maximal tree *T*, the group L(A) is free with free basis

 $\{x_e = label(T[q_0, \iota e] \cdot e \cdot T[\tau e, q_0]) \in L(\mathcal{A}) \mid e \in EX - ET\},\$

where T[p, q] denotes the geodesic in T from p to q. In particular, rk(L(A)) = 1 - |V| + |E|.

▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ● ● ●

Constructing the automaton from the subgroup

Given $H = \langle w_1, \ldots, w_n \rangle \in F(A)$, construct the flower automaton, denoted $\mathcal{F}(H)$.

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

Clearly, $L(\mathcal{F}(H)) = H$.

... But $\mathcal{F}(H)$ is not in general deterministic...

 1. Free-abelian-by-free groups
 Stallings' automata
 Vectored Stallings' automata
 Membership
 Intersection

 00000
 00000
 0000
 0000
 00000000000

Constructing the automaton from the subgroup

Given $H = \langle w_1, \ldots, w_n \rangle \in F(A)$, construct the flower automaton, denoted $\mathcal{F}(H)$.

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

Clearly, $L(\mathcal{F}(H)) = H$.

... But $\mathcal{F}(H)$ is not in general deterministic...

 1. Free-abelian-by-free groups
 Stallings' automata
 Vectored Stallings' automata
 Membership
 Intersection

 00000
 00000
 0000
 0000
 00000000000

Constructing the automaton from the subgroup

Given $H = \langle w_1, \ldots, w_n \rangle \in F(A)$, construct the flower automaton, denoted $\mathcal{F}(H)$.

▲□▶ ▲□▶ ▲三▶ ▲三▶ - 三 - のへで

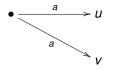
Clearly, $L(\mathcal{F}(H)) = H$.

... But $\mathcal{F}(H)$ is not in general deterministic...



Constructing the automaton from the subgroup

In any automaton A containing the following situation, for $a \in A^{\pm 1}$,



we can fold and identify vertices u and v to obtain

•
$$\longrightarrow U = V$$

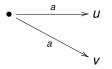
This operation, $\mathcal{A} \rightsquigarrow \mathcal{A}'$, is called a Stallings folding.

(日)



Constructing the automaton from the subgroup

In any automaton A containing the following situation, for $a \in A^{\pm 1}$,



we can fold and identify vertices u and v to obtain

•
$$\longrightarrow U = V$$

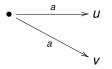
▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

This operation, $\mathcal{A} \rightsquigarrow \mathcal{A}'$, is called a Stallings folding.



Constructing the automaton from the subgroup

In any automaton A containing the following situation, for $a \in A^{\pm 1}$,



we can fold and identify vertices u and v to obtain

•
$$\longrightarrow U = V$$

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

This operation, $\mathcal{A} \rightsquigarrow \mathcal{A}'$, is called a Stallings folding.

Stallings' automata

Vectored Stallings' automata

Membership

Intersection 00000000000000000

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

Constructing the automata from the subgroup

Lemma (Stallings)

If $\mathcal{A} \rightsquigarrow \mathcal{A}'$ is a Stallings folding then $L(\mathcal{A}) = L(\mathcal{A}')$.

Given a f.g. subgroup $H = \langle w_1, \ldots, w_n \rangle \leq F_X$ (we assume w_i are reduced words), do the following:

- 1- Draw the flower automaton,
- 2- Perform successive foldings until obtaining a Stallings automaton, denoted $\Gamma(H)$.

Stallings' automata

Vectored Stallings' automata

Membership

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

Constructing the automata from the subgroup

Lemma (Stallings)

If $\mathcal{A} \rightsquigarrow \mathcal{A}'$ is a Stallings folding then $L(\mathcal{A}) = L(\mathcal{A}')$.

Given a f.g. subgroup $H = \langle w_1, \ldots, w_n \rangle \leq F_X$ (we assume w_i are reduced words), do the following:

- 1- Draw the flower automaton,
- Perform successive foldings until obtaining a Stallings automaton, denoted Γ(H).

Stallings' automata

Vectored Stallings' automata

Membership

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

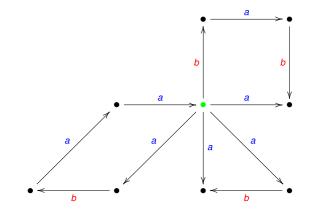
Constructing the automata from the subgroup

Lemma (Stallings)

If $\mathcal{A} \rightsquigarrow \mathcal{A}'$ is a Stallings folding then $L(\mathcal{A}) = L(\mathcal{A}')$.

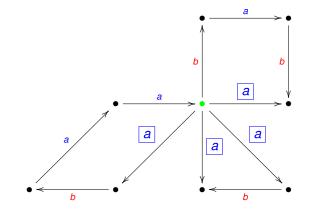
Given a f.g. subgroup $H = \langle w_1, \ldots, w_n \rangle \leq F_X$ (we assume w_i are reduced words), do the following:

- 1- Draw the flower automaton,
- 2- Perform successive foldings until obtaining a Stallings automaton, denoted $\Gamma(H)$.



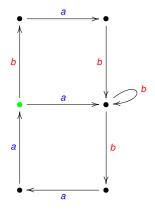
▲□▶ ▲□▶ ▲三▶ ▲三▶ 三三 のへで

Flower(H)



▲□▶ ▲□▶ ▲三▶ ▲三▶ 三三 のへで

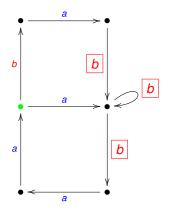
Flower(H)



イロト イポト イヨト イヨト

3

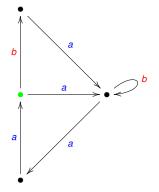
Folding #1



▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

Folding #1.

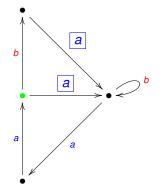
Example: $H = \langle baba^{-1}, aba^{-1}, aba^2 \rangle$





1. Free-abelian-by-free groups Stallings' automata Vectored Stallings' automata Membership Intersection

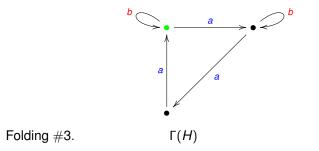
Example: $H = \langle baba^{-1}, aba^{-1}, aba^2 \rangle$



▲□▶ ▲□▶ ▲三▶ ▲三▶ 三三 のへで

Folding #2.

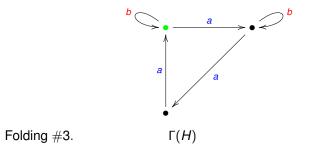




By Stallings Lemma, $L(\Gamma(H)) = H = \langle baba^{-1}, aba^{-1}, aba^2 \rangle$

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

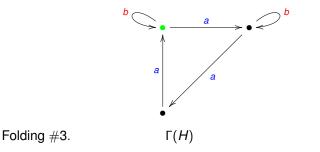




By Stallings Lemma, $L(\Gamma(H)) = H = \langle baba^{-1}, aba^{-1}, aba^{2} \rangle$

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで





By Stallings Lemma, $L(\Gamma(H)) = H = \langle baba^{-1}, aba^{-1}, aba^{2} \rangle$ = $\langle b, aba^{-1}, a^{3} \rangle$

◆□▶ ◆□▶ ◆臣▶ ◆臣▶ ─臣 ─の��

1. Free-abelian-by-free	groups

Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection 00000000000000000

Local confluence

It can be shown that

Proposition

The automaton $\Gamma(H)$ does not depend on the sequence of foldings.

Proposition

The automaton $\Gamma(H)$ does not depend on the generators of H.

Theorem

The following is a well defined bijection:

 $\begin{array}{rcl} \{f.g. \ subgroups \ of \ \mathbb{F}_X\} & \longleftrightarrow & \{ \ Stallings \ X\ -automata \} \\ & H & \mapsto & \Gamma(H) \\ & \mathcal{L}(\mathcal{A}) & \leftarrow & \mathcal{A} \end{array}$

1. Free-abelian-by-free	groups

Stallings' automata

Vectored Stallings' automata

Membership 00

Local confluence

It can be shown that

Proposition

The automaton $\Gamma(H)$ does not depend on the sequence of foldings.

Proposition

The automaton $\Gamma(H)$ does not depend on the generators of H.

Theorem

The following is a well defined bijection:

 $\begin{array}{rcl} \{f.g. \ subgroups \ of \ \mathbb{F}_X\} & \longleftrightarrow & \{ \ Stallings \ X\ -automata \} \\ & H & \mapsto & \Gamma(H) \\ & \mathcal{L}(\mathcal{A}) & \leftarrow & \mathcal{A} \end{array}$

1. Free-abelian-by-free	groups

Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

Local confluence

It can be shown that

Proposition

The automaton $\Gamma(H)$ does not depend on the sequence of foldings.

Proposition

The automaton $\Gamma(H)$ does not depend on the generators of H.

Theorem

The following is a well defined bijection:

 $\begin{array}{rcl} \{ \textit{f.g. subgroups of } \mathbb{F}_X \} & \longleftrightarrow & \{ \textit{Stallings X-automata} \} \\ & H & \mapsto & \Gamma(H) \\ & L(\mathcal{A}) & \leftarrow & \mathcal{A} \end{array}$

000000	000000000000000000000000000000000000000		00	000000000000000000000000000000000000000
1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership	Intersection

Outline

- Free-abelian-by-free groups
- 2 Stallings' automata
- Vectored Stallings' automata
- Membership

5 Intersection

Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection 00000000000000000

(日) (日) (日) (日) (日) (日) (日)

Vectored Stallings' automata

Definition

Let us consider now, vectored X-automata, i.e., X-graphs with vectors assigned at the heads and tails of the edges,



reading $t^{-u_1} a t^{u_2} = a t^{u_2-u_1A}$ (and the inverse if traversed backwards). ... plus a subspace $L \leq \mathbb{Z}^m$ attached to the basepoint.

Example

For a f.g. subgroup $H = \langle w_1 t^{u_1}, \ldots, w_r t^{u_r} \rangle$ of $\mathbb{G}_{\mathbf{A}} = \mathbb{F}_n \ltimes_{A_1, \ldots, A_n} \mathbb{Z}^m$, we can also construct a flower automaton.

Stallings' automata

Vectored Stallings' automata

Membership 00

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

Vectored Stallings' automata

Definition

Let us consider now, vectored X-automata, i.e., X-graphs with vectors assigned at the heads and tails of the edges,



reading $t^{-u_1} a t^{u_2} = a t^{u_2-u_1A}$ (and the inverse if traversed backwards). ... plus a subspace $L \leq \mathbb{Z}^m$ attached to the basepoint.

Example

For a f.g. subgroup $H = \langle w_1 t^{u_1}, \ldots, w_r t^{u_r} \rangle$ of $\mathbb{G}_{\mathbf{A}} = \mathbb{F}_n \ltimes_{A_1, \ldots, A_n} \mathbb{Z}^m$, we can also construct a flower automaton.

Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

Vectored Stallings' automata

Definition

Let us consider now, vectored X-automata, i.e., X-graphs with vectors assigned at the heads and tails of the edges,



reading $t^{-u_1} a t^{u_2} = a t^{u_2-u_1A}$ (and the inverse if traversed backwards). ... plus a subspace $L \leq \mathbb{Z}^m$ attached to the basepoint.

Example

For a f.g. subgroup $H = \langle w_1 t^{u_1}, \ldots, w_r t^{u_r} \rangle$ of $\mathbb{G}_{\mathbf{A}} = \mathbb{F}_n \ltimes_{A_1, \ldots, A_n} \mathbb{Z}^m$, we can also construct a flower automaton.

Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection 00000000000000000

Vectored Stallings' automata

Definition

Let us consider now, vectored X-automata, i.e., X-graphs with vectors assigned at the heads and tails of the edges,



reading $t^{-u_1} a t^{u_2} = a t^{u_2-u_1 A}$ (and the inverse if traversed backwards). ... plus a subspace $L \leq \mathbb{Z}^m$ attached to the basepoint (corresponding to the purely abelian elements).

Example

For a f.g. subgroup $H = \langle w_1 t^{u_1}, \dots, w_r t^{u_r}, t^{v_1}, \dots, t^{v_s} \rangle$ of $\mathbb{G}_{\mathbf{A}} = \mathbb{F}_n \ltimes_{\mathbf{A}_1, \dots, \mathbf{A}_n} \mathbb{Z}^m$, we can also construct a flower automaton.

1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection

Definition

We need now some extra operations to allow moving abelian mass arround:

- edge moves,
- vertex moves,
- vertex moves at the basepoint,
- open foldings,
- closed foldings,
- increase L to its closure by the labels of all closed paths at •.

Definition

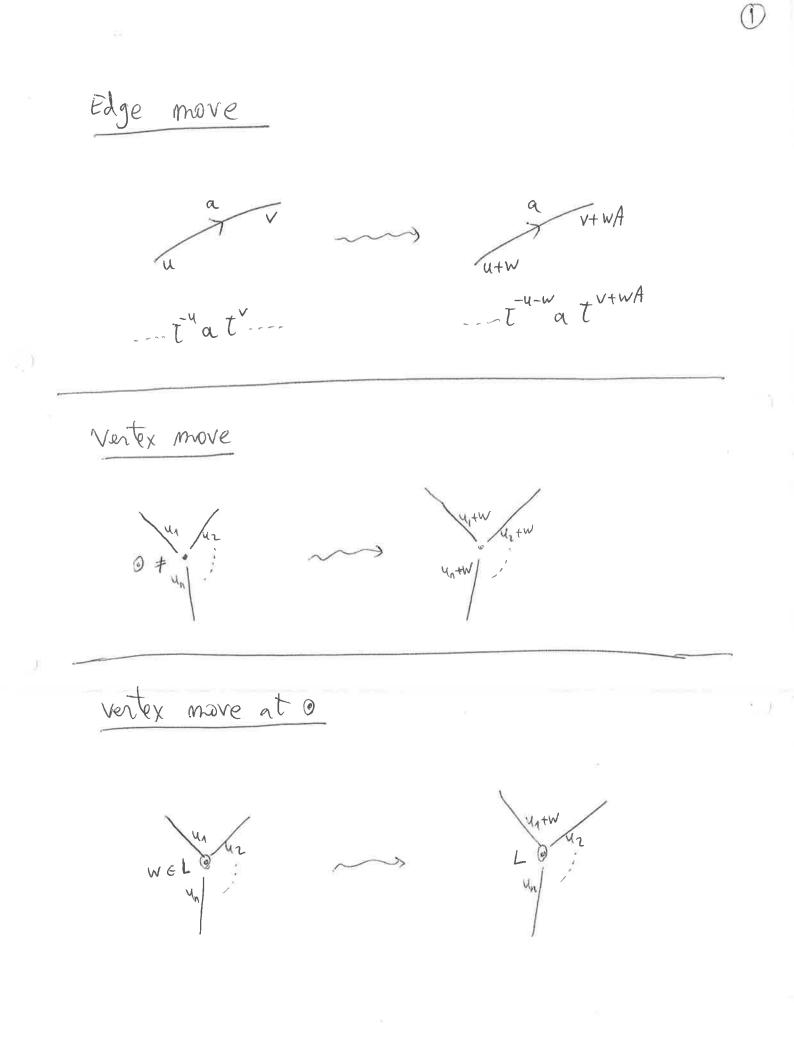
A I I'				
1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection

Definition

We need now some extra operations to allow moving abelian mass arround:

- edge moves,
- vertex moves,
- vertex moves at the basepoint,
- open foldings,
- closed foldings,
- increase L to its closure by the labels of all closed paths at •.

Definition



		00000				
1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership	Intersection		

Definition

We need now some extra operations to allow moving abelian mass arround:

- edge moves,
- vertex moves,
- vertex moves at the basepoint,
- open foldings,
- closed foldings,
- increase L to its closure by the labels of all closed paths at •.

Definition

open folding $u_1 \qquad u_2 \qquad u_1 \qquad u_2 \qquad u_1 \qquad u_1 \qquad u_1 \qquad u_1 \qquad u_1 \qquad u_1 \qquad u_2 \qquad u_1 \qquad u_1 \qquad u_1 \qquad u_2 \qquad u_1 \qquad u_1 \qquad u_1 \qquad u_2 \qquad u_1 \qquad u_1 \qquad u_2 \qquad u_1 \qquad u_2 \qquad u_1 \qquad u_1 \qquad u_2 \qquad u_2 \qquad u_1 \qquad u_2 \qquad u_2 \qquad u_1 \qquad u_2 \qquad u_1 \qquad u_2 \qquad u_1 \qquad u_2 \qquad u_2 \qquad u_2 \qquad u_1 \qquad u_2 \qquad u_2 \qquad u_2 \qquad u_2 \qquad u_1 \qquad u_2 \qquad u_2 \qquad u_2 \qquad u_1 \qquad u_2 \qquad u_2 \qquad u_2 \qquad u_1 \qquad u_2 \qquad u_2$ closed folling $u_{1} \qquad u_{2} \qquad u_{1} \qquad u_{2} \qquad u_{2$ $wt^{u}t^{u}at^{u}t^{v}s^{-1}t^{u}t^{w}t^{-1} =$ $= waa^{-1}W^{-1} \cdot t^{(u-u_3)}W^{-1} + (u_2 - u_5)A^{-1}W^{-1} + (u_3 - u_3)W^{-1}$ $= t^{(u_2 - u_5)} A^{-1} W^{-1}$

.

000000	000000000000000000000000000000000000000		00	000000000000000000000000000000000000000
1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership	Intersection

Definition

We need now some extra operations to allow moving abelian mass arround:

- edge moves,
- vertex moves,
- vertex moves at the basepoint,
- open foldings,
- closed foldings,
- increase L to its closure by the labels of all closed paths at •.

Definition

1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection

Definition

We need now some extra operations to allow moving abelian mass arround:

- edge moves,
- vertex moves,
- vertex moves at the basepoint,
- open foldings,
- closed foldings,
- increase L to its closure by the labels of all closed paths at •.

Definition

1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection

Definition

We need now some extra operations to allow moving abelian mass arround:

- edge moves,
- vertex moves,
- vertex moves at the basepoint,
- open foldings,
- closed foldings,
- increase L to its closure by the labels of all closed paths at •.

Definition

1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection

Definition

We need now some extra operations to allow moving abelian mass arround:

- edge moves,
- vertex moves,
- vertex moves at the basepoint,
- open foldings,
- closed foldings,
- increase L to its closure by the labels of all closed paths at •.

Definition

A vectored Stallings A-automata is a connected and trim vectored A-automata satisfying:

(i) A is deterministic,

(ii) L is invariant by the labels of all closed paths at •,

(iii) vectors are zero everywhere except, maybe, at the heads of edges outside a chosen maximal tree T.

1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata ○○○○●	Membership 00	Intersection
The bijection				

Lemma

With repeated use of the above operations, any vectored X-automata A can be converted into a vectored Stallings X-automata A'.

emma

For $H \leq \mathbb{G}_A$, the result of folding $\mathcal{F}I(H)$, say $\Gamma(H)$, is uniquely determined by the subgroup H, modulo the choice of the maximal tree, and with all vectors around understood 'modulo L'.

Theorem (Delgado–V., 2016)

The following map is a bijection:

 $\{ \begin{array}{rcl} \textit{Subgroups of } \mathbb{G}_{A} \} & \longleftrightarrow & \{ \textit{Vectored Stallings X-automata} \} \\ H & \mapsto & \Gamma(H) \\ L(\mathcal{A}) & \leftarrow & \mathcal{A} \end{array}$

1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection
The bijection				

Lemma

With repeated use of the above operations, any vectored X-automata A can be converted into a vectored Stallings X-automata A'.

Lemma

For $H \leq \mathbb{G}_{\mathbf{A}}$, the result of folding $\mathcal{F}I(H)$, say $\Gamma(H)$, is uniquely determined by the subgroup H, modulo the choice of the maximal tree, and with all vectors around understood 'modulo L'.

Theorem (Delgado–V., 2016)

The following map is a bijection:

 $\begin{array}{rcl} \{ \textit{Subgroups of } \mathbb{G}_{A} \} & \longleftrightarrow & \{ \textit{Vectored Stallings X-automata} \} \\ & H & \mapsto & \Gamma(H) \\ & \mathcal{L}(\mathcal{A}) & \leftarrow & \mathcal{A} \end{array}$

1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata ○000●	Membership 00	Intersection		
The bijection						

Lemma

With repeated use of the above operations, any vectored X-automata A can be converted into a vectored Stallings X-automata A'.

Lemma

For $H \leq \mathbb{G}_A$, the result of folding $\mathcal{F}I(H)$, say $\Gamma(H)$, is uniquely determined by the subgroup H, modulo the choice of the maximal tree, and with all vectors around understood 'modulo L'.

Theorem (Delgado–V., 2016)

The following map is a bijection:

 $\begin{array}{rcl} \{ \textit{Subgroups of } \mathbb{G}_{\textbf{A}} \} & \longleftrightarrow & \{ \textit{Vectored Stallings X-automata} \} \\ & H & \mapsto & \Gamma(H) \\ & L(\mathcal{A}) & \nleftrightarrow & \mathcal{A} \end{array}$

1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership ●○	Intersection 0000000000000000
Outline				

- Free-abelian-by-free groups
 - 2 Stallings' automata
- 3 Vectored Stallings' automata
- 4 Membership
- 5 Intersection

1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership ○●	Intersection
Membership				

Membership is solvable in free-abelian-by-free groups.

- 1- draw the flower automaton $\mathcal{F}I(H)$;
- 2- perform successive foldings until obtaining the vectored Stallings X-automaton $\Gamma(H)$;
- 3- if w is not readable as closed path at \bullet , answer **NO**;
- 4- otherwise, compute the full label of such a close path, say wt^v;
- 5- if $u v \in L$ answer **YES**; otherwise, answer **NO**.

1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership ○●	Intersection
Membership				

Membership is solvable in free-abelian-by-free groups.

- 1- draw the flower automaton $\mathcal{F}I(H)$;
- 2- perform successive foldings until obtaining the vectored Stallings X-automaton $\Gamma(H)$;
- 3- if w is not readable as closed path at \bullet , answer **NO**;
- 4- otherwise, compute the full label of such a close path, say wt^v;
- 5- if $u v \in L$ answer **YES**; otherwise, answer **NO**.

1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership ○●	Intersection
Membership				

Membership is solvable in free-abelian-by-free groups.

- 1- draw the flower automaton $\mathcal{F}I(H)$;
- 2- perform successive foldings until obtaining the vectored Stallings X-automaton $\Gamma(H)$;
- 3- if w is not readable as closed path at \bullet , answer **NO**;
- 4- otherwise, compute the full label of such a close path, say wt^v;
- 5- if $u v \in L$ answer **YES**; otherwise, answer **NO**.

1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership ○●	Intersection
Membership				

Membership is solvable in free-abelian-by-free groups.

- 1- draw the flower automaton $\mathcal{F}I(H)$;
- 2- perform successive foldings until obtaining the vectored Stallings X-automaton Γ(H);
- 3- if w is not readable as closed path at \bullet , answer **NO**;
- 4- otherwise, compute the full label of such a close path, say wt^v;
- 5- if $u v \in L$ answer **YES**; otherwise, answer **NO**.

Membershin				
1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership	Intersection

Membership is solvable in free-abelian-by-free groups.

Proof. Given $wt^{u} \in \mathbb{G}_{A}$ and $H = \langle w_{1}t^{u_{1}}, \ldots, w_{r}t^{u_{r}} \rangle \leq \mathbb{G}_{A}$, do the following:

- 1- draw the flower automaton $\mathcal{F}I(H)$;
- 2- perform successive foldings until obtaining the vectored Stallings X-automaton Γ(H);
- 3- if w is not readable as closed path at •, answer **NO**;
- 4- otherwise, compute the full label of such a close path, say wt^{v} ; 5- if $u - v \in L$ answer **YES**; otherwise, answer **NO**.

(日) (日) (日) (日) (日) (日) (日)

1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership ○●	Intersection
Membership				

Membership is solvable in free-abelian-by-free groups.

Proof. Given $wt^{u} \in \mathbb{G}_{A}$ and $H = \langle w_{1}t^{u_{1}}, \ldots, w_{r}t^{u_{r}} \rangle \leq \mathbb{G}_{A}$, do the following:

- 1- draw the flower automaton $\mathcal{F}I(H)$;
- 2- perform successive foldings until obtaining the vectored Stallings X-automaton Γ(H);
- 3- if w is not readable as closed path at •, answer **NO**;
- 4- otherwise, compute the full label of such a close path, say wt^v;

(日) (日) (日) (日) (日) (日) (日)

5- if $u - v \in L$ answer **YES**; otherwise, answer **NO**.

Membershin				
1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership	Intersection

Membership is solvable in free-abelian-by-free groups.

- 1- draw the flower automaton $\mathcal{F}I(H)$;
- 2- perform successive foldings until obtaining the vectored Stallings X-automaton Γ(H);
- 3- if w is not readable as closed path at •, answer **NO**;
- 4- otherwise, compute the full label of such a close path, say wt^v;
- 5- if $u v \in L$ answer **YES**; otherwise, answer **NO**.

1. Free-abelian-by-free	groups

Vectored Stallings' automata

lembership

Intersection

••••••••

Outline

- Free-abelian-by-free groups
- 2 Stallings' automata
- 3 Vectored Stallings' automata
- Membership





Vectored Stallings' automata

Membership 00

・ロット (雪) (日) (日) (日)

The Subgroup Intersection Problem

(Caution!)

The groups \mathbb{G}_A are NOT Howson, in general.

Definition (The Subgroup Intersection Problem for G)

Input: $g_1, \ldots, g_r, g'_1, \ldots, g'_s \in G$ *Decide:* $\langle g_1, \ldots, g_r \rangle \cap \langle g'_1, \ldots, g'_s \rangle$ is f.g. and, if so, compute generators.

Theorem (Delgado–V., 2017)

The Subgroup Intersection Problem is solvable in $\mathbb{F}_n \times \mathbb{Z}^m$.

Question

Vectored Stallings' automata

Membership 00

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

The Subgroup Intersection Problem

(Caution!)

The groups \mathbb{G}_{A} are **NOT** Howson, in general.

Definition (The Subgroup Intersection Problem for G)

Input: $g_1, \ldots, g_r, g'_1, \ldots, g'_s \in G$ Decide: $\langle g_1, \ldots, g_r \rangle \cap \langle g'_1, \ldots, g'_s \rangle$ is f.g. and, if so, compute generators.

Theorem (Delgado–V., 2017)

The Subgroup Intersection Problem is solvable in $\mathbb{F}_n imes \mathbb{Z}^m$.

Question

Vectored Stallings' automata

Membership 00

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

The Subgroup Intersection Problem

(Caution!)

The groups \mathbb{G}_{A} are **NOT** Howson, in general.

Definition (The Subgroup Intersection Problem for G)

Input: $g_1, \ldots, g_r, g'_1, \ldots, g'_s \in G$ **Decide:** $\langle g_1, \ldots, g_r \rangle \cap \langle g'_1, \ldots, g'_s \rangle$ is f.g. and, if so, compute generators.

Theorem (Delgado–V., 2017)

The Subgroup Intersection Problem is solvable in $\mathbb{F}_n \times \mathbb{Z}^m$.

Question

Vectored Stallings' automata

Membership 00

The Subgroup Intersection Problem

(Caution!)

The groups \mathbb{G}_{A} are **NOT** Howson, in general.

Definition (The Subgroup Intersection Problem for G)

Input: $g_1, \ldots, g_r, g'_1, \ldots, g'_s \in G$ Decide: $\langle g_1, \ldots, g_r \rangle \cap \langle g'_1, \ldots, g'_s \rangle$ is f.g. and, if so, compute generators.

Theorem (Delgado-V., 2017)

The Subgroup Intersection Problem is solvable in $\mathbb{F}_n \times \mathbb{Z}^m$.

Question

1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection
The key poir	nt			

$H \cap K$ is f.g. $\Leftrightarrow (H \cap K)\pi$ is f.g.

and $H\pi \cap K\pi$ is f.g. (because \mathbb{F}_n is Howson) ... BUT

 $1 \leqslant (H \cap K)\pi \leqslant H\pi \cap K\pi,$

with possibly strict inequality. In the case $\mathbb{F}_n \times \mathbb{Z}^m$ (not true in general),

 $1 \neq (H \cap K)\pi \trianglelefteq H\pi \cap K\pi.$

So,

1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection
The key poir	nt			

 $H \cap K$ is f.g. $\Leftrightarrow (H \cap K)\pi$ is f.g.

and $H\pi \cap K\pi$ is f.g. (because \mathbb{F}_n is Howson)... BUT

 $1 \leqslant (H \cap K)\pi \leqslant H\pi \cap K\pi,$

with possibly strict inequality. In the case $\mathbb{F}_n \times \mathbb{Z}^m$ (not true in general),

 $1 \neq (H \cap K)\pi \trianglelefteq H\pi \cap K\pi.$

So,

1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection
The key poir	nt			

 $H \cap K$ is f.g. $\Leftrightarrow (H \cap K)\pi$ is f.g.

and $H\pi \cap K\pi$ is f.g. (because \mathbb{F}_n is Howson)... BUT

 $1 \leqslant (H \cap K)\pi \leqslant H\pi \cap K\pi,$

with possibly strict inequality. In the case $\mathbb{F}_n \times \mathbb{Z}^m$ (not true in general),

 $1 \neq (H \cap K)\pi \trianglelefteq H\pi \cap K\pi.$

So,

1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection
The key poir	nt			

 $H \cap K$ is f.g. $\Leftrightarrow (H \cap K)\pi$ is f.g.

and $H\pi \cap K\pi$ is f.g. (because \mathbb{F}_n is Howson)... BUT

 $1 \leqslant (H \cap K)\pi \leqslant H\pi \cap K\pi,$

with possibly strict inequality. In the case $\mathbb{F}_n \times \mathbb{Z}^m$ (not true in general),

 $1 \neq (H \cap K)\pi \trianglelefteq H\pi \cap K\pi.$

So,

 $H \cap K$ is f.g. $\Leftrightarrow (H \cap K)\pi$ is f.g. $\Leftrightarrow (H \cap K)\pi \leq_{f.i.} H\pi \cap K\pi$.

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection
The key poir	nt			

 $H \cap K$ is f.g. $\Leftrightarrow (H \cap K)\pi$ is f.g.

and $H\pi \cap K\pi$ is f.g. (because \mathbb{F}_n is Howson)... BUT

 $1 \leqslant (H \cap K)\pi \leqslant H\pi \cap K\pi,$

with possibly strict inequality. In the case $\mathbb{F}_n \times \mathbb{Z}^m$ (not true in general),

 $1 \neq (H \cap K)\pi \trianglelefteq H\pi \cap K\pi.$

So,

Vectored Stallings' automata

Membership 00

The free case: pullback of graphs

To compute intersections in \mathbb{F}_n , we have the well-known technique of the pull-back of graphs: given $H, K \leq_{fg} \mathbb{F}_n$,

Let us see an example with the subgroups $H = \langle x^3, yx \rangle$ and $K = \langle x^2, yxy^{-1} \rangle$ in $\mathbb{F}_2 = \langle x, y | - \rangle$

・ロト・西ト・ヨト・ヨー シック

Vectored Stallings' automata

Membership 00 Intersection

The free case: pullback of graphs

To compute intersections in \mathbb{F}_n , we have the well-known technique of the pull-back of graphs: given $H, K \leq_{fg} \mathbb{F}_n$,

$$\begin{array}{rcccc} H & \to & \Gamma(H) & \searrow \\ K & \to & \Gamma(K) & \nearrow \end{array} \quad & \Gamma(H) \times \Gamma(K) & \to & H \cap K \end{array}$$

Let us see an example with the subgroups $H = \langle x^3, yx \rangle$ and $K = \langle x^2, yxy^{-1} \rangle$ in $\mathbb{F}_2 = \langle x, y | - \rangle$

・ロト・西ト・山下・山下・山下・

Vectored Stallings' automata

Membership 00 Intersection

The free case: pullback of graphs

To compute intersections in \mathbb{F}_n , we have the well-known technique of the pull-back of graphs: given $H, K \leq_{fg} \mathbb{F}_n$,

$$\begin{array}{rcccc} H & \to & \Gamma(H) & \searrow \\ K & \to & \Gamma(K) & \nearrow \end{array} \quad & \Gamma(H) \times \Gamma(K) & \to & H \cap K \end{array}$$

Let us see an example with the subgroups $H = \langle x^3, yx \rangle$ and $K = \langle x^2, yxy^{-1} \rangle$ in $\mathbb{F}_2 = \langle x, y | - \rangle$

・ロト・西ト・山下・山下・山下・

Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

▲□▶ ▲□▶ ▲□▶ ▲□▶ = 三 のへで

The free case: pullback of graphs

Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

The free case: pullback of graphs

Let
$$H = \langle x^3, yx \rangle$$
, $K = \langle x^2, yxy^{-1} \rangle \leqslant \mathbb{F}_2 = \langle x, y \mid - \rangle$



Vectored Stallings' automata

Membership 00

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

The free case: pullback of graphs

Let
$$H = \langle x^3, yx \rangle$$
, $K = \langle x^2, yxy^{-1} \rangle \leq \mathbb{F}_2 = \langle x, y \mid - \rangle$

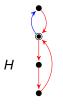
Stallings' automata

Vectored Stallings' automata

Membership 00

The free case: pullback of graphs

Let
$$H = \langle x^3, yx \rangle$$
, $K = \langle x^2, yxy^{-1} \rangle \leq \mathbb{F}_2 = \langle x, y \mid - \rangle$





Stallings' automata

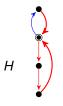
Vectored Stallings' automata

Membership 00

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

The free case: pullback of graphs

Let
$$H = \langle x^3, yx \rangle$$
, $K = \langle x^2, yxy^{-1} \rangle \leq \mathbb{F}_2 = \langle x, y \mid - \rangle$



Vectored Stallings' automata

Membership 00

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

The free case: pullback of graphs

Let
$$H = \langle x^3, yx \rangle$$
, $K = \langle x^2, yxy^{-1} \rangle \leq \mathbb{F}_2 = \langle x, y \mid - \rangle$



Stallings' automata

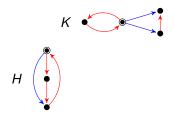
Vectored Stallings' automata

Membership 00

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

The free case: pullback of graphs

Let
$$H = \langle x^3, yx \rangle$$
, $K = \langle x^2, yxy^{-1} \rangle \leq \mathbb{F}_2 = \langle x, y \mid - \rangle$



Stallings' automata

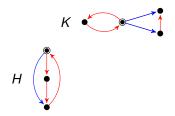
Vectored Stallings' automata

Membership 00

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

The free case: pullback of graphs

Let
$$H = \langle x^3, yx \rangle$$
, $K = \langle x^2, yxy^{-1} \rangle \leq \mathbb{F}_2 = \langle x, y \mid - \rangle$



Stallings' automata

Vectored Stallings' automata

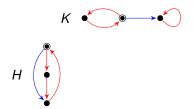
Membership 00

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

Intersection

The free case: pullback of graphs

Let
$$H = \langle x^3, yx \rangle$$
, $K = \langle x^2, yxy^{-1} \rangle \leq \mathbb{F}_2 = \langle x, y \mid - \rangle$



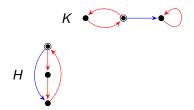
Intersection

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

The free case: pullback of graphs

Let
$$H = \langle x^3, yx \rangle$$
, $K = \langle x^2, yxy^{-1} \rangle \leq \mathbb{F}_2 = \langle x, y \mid - \rangle$

Firstly, we compute the Stallings automata $\Gamma(H)$, $\Gamma(K)$. To compute $H \cap K$ we build the pull-back $\Gamma(H) \times \Gamma(K)$:



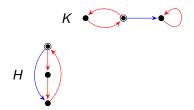
Intersection

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

The free case: pullback of graphs

Let
$$H = \langle x^3, yx \rangle$$
, $K = \langle x^2, yxy^{-1} \rangle \leq \mathbb{F}_2 = \langle x, y \mid - \rangle$

Firstly, we compute the Stallings automata $\Gamma(H)$, $\Gamma(K)$. To compute $H \cap K$ we build the pull-back $\Gamma(H) \times \Gamma(K)$:

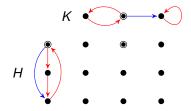


The free case: pullback of graphs

Let
$$H = \langle x^3, yx \rangle$$
, $K = \langle x^2, yxy^{-1} \rangle \leqslant \mathbb{F}_2 = \langle x, y \mid - \rangle$

Firstly, we compute the Stallings automata $\Gamma(H)$, $\Gamma(K)$. To compute $H \cap K$ we build the pull-back $\Gamma(H) \times \Gamma(K)$:

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

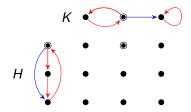


The free case: pullback of graphs

Let
$$H = \langle x^3, yx \rangle$$
, $K = \langle x^2, yxy^{-1} \rangle \leqslant \mathbb{F}_2 = \langle x, y \mid - \rangle$

Firstly, we compute the Stallings automata $\Gamma(H)$, $\Gamma(K)$. To compute $H \cap K$ we build the pull-back $\Gamma(H) \times \Gamma(K)$:

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

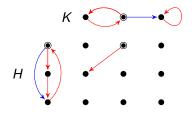


Membership 00 ◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

The free case: pullback of graphs

Let
$$H = \langle x^3, yx \rangle$$
, $K = \langle x^2, yxy^{-1} \rangle \leq \mathbb{F}_2 = \langle x, y \mid - \rangle$

Firstly, we compute the Stallings automata $\Gamma(H)$, $\Gamma(K)$. To compute $H \cap K$ we build the pull-back $\Gamma(H) \times \Gamma(K)$:



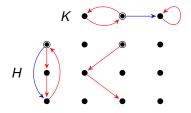
Membership 00 Intersection

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

The free case: pullback of graphs

Let
$$H = \langle x^3, yx \rangle$$
, $K = \langle x^2, yxy^{-1} \rangle \leq \mathbb{F}_2 = \langle x, y \mid - \rangle$

Firstly, we compute the Stallings automata $\Gamma(H)$, $\Gamma(K)$. To compute $H \cap K$ we build the pull-back $\Gamma(H) \times \Gamma(K)$:

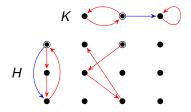


Vectored Stallings' automata

Membership 00 ◆□▶ ◆□▶ ◆□▶ ◆□▶ ● ● ● ●

The free case: pullback of graphs

Let
$$H = \langle x^3, yx \rangle$$
, $K = \langle x^2, yxy^{-1} \rangle \leqslant \mathbb{F}_2 = \langle x, y \mid - \rangle$



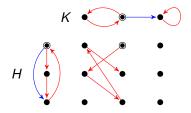
Vectored Stallings' automata

Membership 00 Intersection

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

The free case: pullback of graphs

Let
$$H = \langle x^3, yx \rangle$$
, $K = \langle x^2, yxy^{-1} \rangle \leqslant \mathbb{F}_2 = \langle x, y \mid - \rangle$

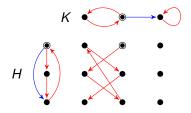


Vectored Stallings' automata

Membership 00 ◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

The free case: pullback of graphs

Let
$$H = \langle x^3, yx \rangle$$
, $K = \langle x^2, yxy^{-1} \rangle \leqslant \mathbb{F}_2 = \langle x, y \mid - \rangle$



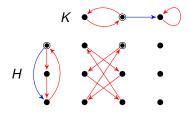
Vectored Stallings' automata

Membership 00 Intersection

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

The free case: pullback of graphs

Let
$$H = \langle x^3, yx \rangle$$
, $K = \langle x^2, yxy^{-1} \rangle \leqslant \mathbb{F}_2 = \langle x, y \mid - \rangle$



Stallings' automata

Vectored Stallings' automata

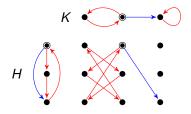
Membership

Intersection

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

The free case: pullback of graphs

Let
$$H = \langle x^3, yx \rangle$$
, $K = \langle x^2, yxy^{-1} \rangle \leq \mathbb{F}_2 = \langle x, y \mid - \rangle$



Stallings' automata

Vectored Stallings' automata

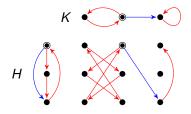
Membership

・ コット (雪) (小田) (コット 日)

Intersection

The free case: pullback of graphs

Let
$$H = \langle x^3, yx \rangle$$
, $K = \langle x^2, yxy^{-1} \rangle \leqslant \mathbb{F}_2 = \langle x, y \mid - \rangle$



. Free-abelian-by-free groups Stallings' aut 000000 0000000

Stallings' automata

Vectored Stallings' automata

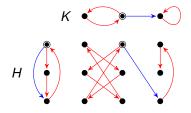
Membership 00

・ コット (雪) (小田) (コット 日)

Intersection

The free case: pullback of graphs

Let
$$H = \langle x^3, yx \rangle$$
, $K = \langle x^2, yxy^{-1} \rangle \leqslant \mathbb{F}_2 = \langle x, y \mid - \rangle$



. Free-abelian-by-free groups Stallings' auton

Stallings' automata

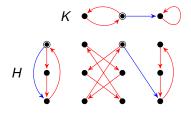
Vectored Stallings' automata

Membership 00 Intersection

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

The free case: pullback of graphs

Let
$$H = \langle x^3, yx \rangle$$
, $K = \langle x^2, yxy^{-1} \rangle \leq \mathbb{F}_2 = \langle x, y \mid - \rangle$

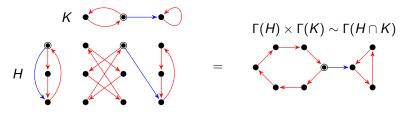


1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection
		1		

The free case: pullback of graphs

Let
$$H = \langle x^3, yx \rangle$$
, $K = \langle x^2, yxy^{-1} \rangle \leq \mathbb{F}_2 = \langle x, y \mid - \rangle$

Firstly, we compute the Stallings automata $\Gamma(H)$, $\Gamma(K)$. To compute $H \cap K$ we build the pull-back $\Gamma(H) \times \Gamma(K)$:



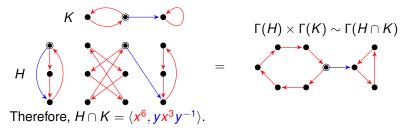
◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection
		1		

The free case: pullback of graphs

Let
$$H = \langle x^3, yx \rangle$$
, $K = \langle x^2, yxy^{-1} \rangle \leq \mathbb{F}_2 = \langle x, y \mid - \rangle$

Firstly, we compute the Stallings automata $\Gamma(H)$, $\Gamma(K)$. To compute $H \cap K$ we build the pull-back $\Gamma(H) \times \Gamma(K)$:



◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection
Intersections	s in $\mathbb{F}_n \times \mathbb{Z}^m$			

◆□▶ ◆□▶ ◆ □▶ ◆ □▶ ● □ ● ● ● ●

1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection
Intercontion				

Intersections in $\mathbb{F}_n \times \mathbb{Z}^m$

Let $H = \langle t^{L_H}, \mathbf{x}^3 t^{\mathbf{a}}, \mathbf{y}\mathbf{x} \rangle$,



1. Free-abelian-by-free gr	oups	Stallings' automata			Vectored Stallings' automata	a Membership 00	Intersection
				m			

Intersections in $\mathbb{F}_n \times \mathbb{Z}^m$

Let $H = \langle t^{L_H}, \mathbf{x}^3 t^{\mathbf{a}}, \mathbf{y} \mathbf{x} \rangle, K = \langle t^{L_K}, \mathbf{x}^2 t^{\mathbf{d}}, \mathbf{y} \mathbf{x} \mathbf{y}^{-1} \rangle$

ata Vectored

Vectored Stallings' automata

Membership 00 Intersection

▲□▶▲□▶▲□▶▲□▶ □ のQ@

Intersections in $\mathbb{F}_n \times \mathbb{Z}^m$

ata Vectored

Vectored Stallings' automata

Membership 00 Intersection

▲□▶▲□▶▲□▶▲□▶ □ のQ@

Intersections in $\mathbb{F}_n \times \mathbb{Z}^m$

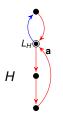
Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

Intersections in $\mathbb{F}_n \times \mathbb{Z}^m$

Let $H = \langle t^{L_{H}}, \mathbf{x}^{3} t^{\mathbf{a}}, \mathbf{y}\mathbf{x} \rangle$, $K = \langle t^{L_{K}}, \mathbf{x}^{2} t^{\mathbf{d}}, \mathbf{y}\mathbf{x}\mathbf{y}^{-1} \rangle \leqslant \mathbb{F}_{2} \times \mathbb{Z}^{2}$



▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへで

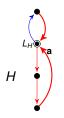
Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

▲□▶▲□▶▲□▶▲□▶ □ のQ@

Intersections in $\mathbb{F}_n \times \mathbb{Z}^m$



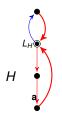
Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

▲□▶▲□▶▲□▶▲□▶ □ のQ@

Intersections in $\mathbb{F}_n \times \mathbb{Z}^m$



Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

Intersections in $\mathbb{F}_n \times \mathbb{Z}^m$

Let $H = \langle t^{\mathcal{L}_{H}}, \mathbf{x}^{3} t^{a}, \mathbf{y}\mathbf{x} \rangle, \, \mathcal{K} = \langle t^{\mathcal{L}_{\mathcal{K}}}, \mathbf{x}^{2} t^{d}, \mathbf{y}\mathbf{x}\mathbf{y}^{-1} \rangle \leqslant \mathbb{F}_{2} \times \mathbb{Z}^{2}$





Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

Intersections in $\mathbb{F}_n \times \mathbb{Z}^m$

Let $H = \langle t^{\mathcal{L}_{H}}, \mathbf{x}^{3} t^{a}, \mathbf{y}\mathbf{x} \rangle, \, \mathcal{K} = \langle t^{\mathcal{L}_{\mathcal{K}}}, \mathbf{x}^{2} t^{d}, \mathbf{y}\mathbf{x}\mathbf{y}^{-1} \rangle \leqslant \mathbb{F}_{2} \times \mathbb{Z}^{2}$





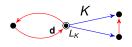
Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

Intersections in $\mathbb{F}_n \times \mathbb{Z}^m$

Let $H = \langle t^{L_H}, \mathbf{x}^3 t^{\mathbf{a}}, \mathbf{y}\mathbf{x} \rangle$, $K = \langle t^{L_K}, \mathbf{x}^2 t^{\mathbf{d}}, \mathbf{y}\mathbf{x}\mathbf{y}^{-1} \rangle \leqslant \mathbb{F}_2 \times \mathbb{Z}^2$





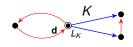
▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへで

Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

Intersections in $\mathbb{F}_n \times \mathbb{Z}^m$







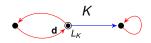
Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

Intersections in $\mathbb{F}_n \times \mathbb{Z}^m$

Let $H = \langle t^{L_H}, \mathbf{x}^3 t^{\mathbf{a}}, \mathbf{y}\mathbf{x} \rangle$, $K = \langle t^{L_K}, \mathbf{x}^2 t^{\mathbf{d}}, \mathbf{y}\mathbf{x}\mathbf{y}^{-1} \rangle \leqslant \mathbb{F}_2 \times \mathbb{Z}^2$





▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● のへで

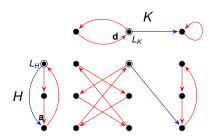
Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

▲□▶▲□▶▲□▶▲□▶ □ のQ@

Intersections in $\mathbb{F}_n \times \mathbb{Z}^m$

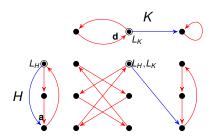


Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

Intersections in $\mathbb{F}_n \times \mathbb{Z}^m$



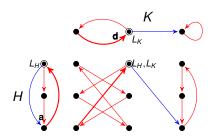
Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

▲□▶▲□▶▲□▶▲□▶ □ のQ@

Intersections in $\mathbb{F}_n \times \mathbb{Z}^m$



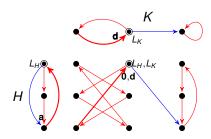
Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

▲□▶▲□▶▲□▶▲□▶ □ のQ@

Intersections in $\mathbb{F}_n \times \mathbb{Z}^m$



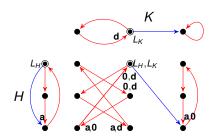
Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

▲□▶▲□▶▲□▶▲□▶ □ のQ@

Intersections in $\mathbb{F}_n \times \mathbb{Z}^m$



Stallings' automata

Vectored Stallings' automata

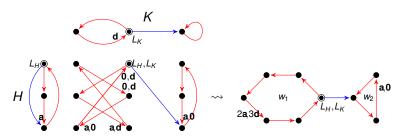
Membership

ヘロト 人間 とくほとくほとう

3

Intersection

Intersections in $\mathbb{F}_n \times \mathbb{Z}^m$



Stallings' automata

Vectored Stallings' automata

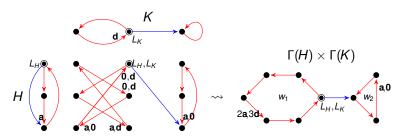
Membership

ヘロト 人間 とくほとくほとう

3

Intersection

Intersections in $\mathbb{F}_n \times \mathbb{Z}^m$



Stallings' automata

Vectored Stallings' automata

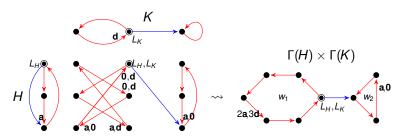
Membership

ヘロト 人間 とくほとくほとう

3

Intersection

Intersections in $\mathbb{F}_n \times \mathbb{Z}^m$



Stallings' automata

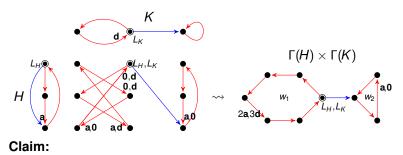
Vectored Stallings' automata

Membership

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

Intersections in $\mathbb{F}_n \times \mathbb{Z}^m$

Let $H = \langle t^{L_{H}}, \mathbf{x}^{3} t^{\mathbf{a}}, \mathbf{y}\mathbf{x} \rangle$, $K = \langle t^{L_{K}}, \mathbf{x}^{2} t^{\mathbf{d}}, \mathbf{y}\mathbf{x}\mathbf{y}^{-1} \rangle \leqslant \mathbb{F}_{2} \times \mathbb{Z}^{2}$



 $H \cap K = \langle u t^{\mathbf{a}} | u t^{\mathbf{a}}$ is componentwise-readable in $\Gamma(H) \times \Gamma(K) \rangle$

Stallings' automata

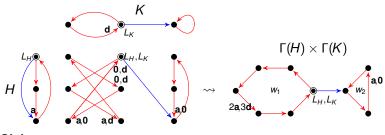
Vectored Stallings' automata

Membership 00 Intersection

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの

Intersections in $\mathbb{F}_n \times \mathbb{Z}^m$

Let $H = \langle t^{L_{H}}, \mathbf{x}^{3} t^{\mathbf{a}}, \mathbf{y}\mathbf{x} \rangle$, $K = \langle t^{L_{K}}, \mathbf{x}^{2} t^{\mathbf{d}}, \mathbf{y}\mathbf{x}\mathbf{y}^{-1} \rangle \leqslant \mathbb{F}_{2} \times \mathbb{Z}^{2}$



Claim:

$$\begin{split} H \cap \mathcal{K} &= \langle u \, t^{\mathbf{a}} \mid u \, t^{\mathbf{a}} \text{ is componentwise-readable in } \Gamma(\mathcal{H}) \times \Gamma(\mathcal{K}) \rangle \\ (\mathcal{H} \cap \mathcal{K}) \pi &= \left\langle w \in \mathbb{F}_{\{w_1, w_2\}} \mid w(w_1 t^{2\mathbf{a}}, w_2 t^{\mathbf{a}}) \, t^{\mathcal{L}_{\mathcal{H}}} \cap w(w_1 t^{3\mathbf{d}}, w_2 t^{\mathbf{0}}) \, t^{\mathcal{L}_{\mathcal{K}}} \neq \varnothing \right\rangle \\ & \rangle \end{split}$$

Stallings' automata

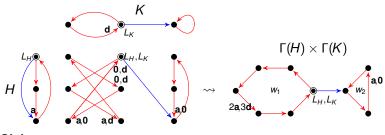
Vectored Stallings' automata

Membership

Intersection

Intersections in $\mathbb{F}_n \times \mathbb{Z}^m$

Let $H = \langle t^{L_{H}}, \mathbf{x}^{3} t^{\mathbf{a}}, \mathbf{y}\mathbf{x} \rangle$, $K = \langle t^{L_{K}}, \mathbf{x}^{2} t^{\mathbf{d}}, \mathbf{y}\mathbf{x}\mathbf{y}^{-1} \rangle \leqslant \mathbb{F}_{2} \times \mathbb{Z}^{2}$



Claim:

$$\begin{split} H \cap K &= \langle u \, t^{\mathbf{a}} \mid u \, t^{\mathbf{a}} \text{ is componentwise-readable in } \Gamma(H) \times \Gamma(K) \rangle \\ (H \cap K)\pi &= \left\langle w \in \mathbb{F}_{\{w_1, w_2\}} \mid w(w_1 t^{2\mathbf{a}}, w_2 t^{\mathbf{a}}) \, t^{\mathcal{L}_{\mathcal{H}}} \cap w(w_1 t^{3\mathbf{d}}, w_2 t^{\mathbf{0}}) \, t^{\mathcal{L}_{\mathcal{K}}} \neq \varnothing \right\rangle \\ &= \left\langle w \in \mathbb{F}_{\{w_1, w_2\}} \mid w^{ab} \begin{bmatrix} 2\mathbf{a} - 3\mathbf{d} \\ \mathbf{a} - \mathbf{0} \end{bmatrix} \in \mathcal{L}_{\mathcal{H}} + \mathcal{L}_{\mathcal{K}} \right\rangle \end{split}$$

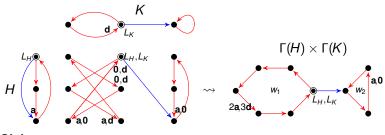
Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

Intersections in $\mathbb{F}_n \times \mathbb{Z}^m$

Let $H = \langle t^{L_{H}}, \mathbf{x}^{3} t^{\mathbf{a}}, \mathbf{y}\mathbf{x} \rangle$, $K = \langle t^{L_{K}}, \mathbf{x}^{2} t^{\mathbf{d}}, \mathbf{y}\mathbf{x}\mathbf{y}^{-1} \rangle \leqslant \mathbb{F}_{2} \times \mathbb{Z}^{2}$

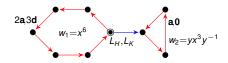


Claim:

$$\begin{split} H \cap K &= \langle u \, t^{\mathbf{a}} \mid u \, t^{\mathbf{a}} \text{ is componentwise-readable in } \Gamma(H) \times \Gamma(K) \rangle \\ (H \cap K)\pi &= \left\langle w \in \mathbb{F}_{\{w_1, w_2\}} \mid w(w_1 t^{2\mathbf{a}}, w_2 t^{\mathbf{a}}) \, t^{L_H} \cap w(w_1 t^{3\mathbf{d}}, w_2 t^{\mathbf{0}}) \, t^{L_K} \neq \varnothing \right\rangle \\ &= \left\langle w \in \mathbb{F}_{\{w_1, w_2\}} \mid w^{ab} \begin{bmatrix} 2\mathbf{a} - 3\mathbf{d} \\ \mathbf{a} - \mathbf{0} \end{bmatrix} \in L_H + L_K \right\rangle \\ &= (L_H + L_K) \mathbf{B}^{-1} \rho^{-1}, \text{ where } \mathbf{B} = \begin{bmatrix} 2\mathbf{a} - 3\mathbf{d} \\ \mathbf{a} - \mathbf{0} \end{bmatrix} \text{ and } \rho = \mathbf{ab}. \end{split}$$

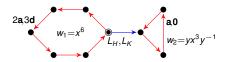
1. Free-abelian-by-fre	e groups	Stallings' automata		Vectored Stallings' automata	Membership 00	Intersection

Intersections in $\mathbb{F}_n \times \mathbb{Z}^m$





1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection 000000000000000000000000000000000000
1				

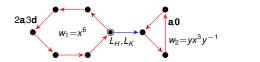


$$\mathbf{B} = \begin{bmatrix} 2\mathbf{a} - 3\mathbf{d} \\ \mathbf{a} - \mathbf{0} \end{bmatrix}$$
$$M = (L_H + L_K)\mathbf{B}^{-1}$$

We have that $(H \cap K)\pi = (L_H + L_K)\mathbf{B}^{-1}\rho^{-1} = M\rho^{-1}$, i.e.,



1. Free-abelian-by-free grou	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection



$$\mathbf{B} = \begin{bmatrix} 2\mathbf{a} - 3\mathbf{d} \\ \mathbf{a} - \mathbf{0} \end{bmatrix}$$
$$M = (L_H + L_K)\mathbf{B}^{-1}$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

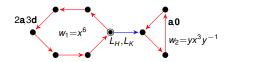
We have that $(H \cap K)\pi = (L_H + L_K)\mathbf{B}^{-1}\rho^{-1} = M\rho^{-1}$, i.e.,

$$\mathbb{F}_{2} \geqslant H\pi \cap K\pi = \mathbb{F}_{\{w_{1},w_{2}\}} \xrightarrow{\rho} \mathbb{Z}^{2} \xrightarrow{\mathbf{B}} \mathbb{Z}^{2}$$

$$\stackrel{\nabla}{\longrightarrow} \mathbb{Z}^{2} \xrightarrow{\nabla} \mathbb{Z}^{2} \xrightarrow{\nabla} \mathbb{Z}^{2}$$

$$1 \neq (H \cap K)\pi = M\rho^{-1} \longleftrightarrow M \xleftarrow{} L_{H} + L_{K}$$

1. Free-abelian-by-free grou	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection 000000000000000000000000000000000000



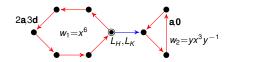
$$\mathbf{B} = \begin{bmatrix} 2\mathbf{a} - 3\mathbf{d} \\ \mathbf{a} - \mathbf{0} \end{bmatrix}$$
$$M = (L_H + L_K)\mathbf{B}^{-1}$$

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

We have that $(H \cap K)\pi = (L_H + L_K)\mathbf{B}^{-1}\rho^{-1} = M\rho^{-1}$, i.e.,

$$\begin{split} \mathbb{F}_{2} \geqslant & H\pi \cap K\pi &= \mathbb{F}_{\{w_{1},w_{2}\}} \xrightarrow{\rho} \mathbb{Z}^{2} \xrightarrow{\mathbf{B}} \mathbb{Z}^{2} \\ & \nabla & \nabla & \nabla \\ & 1 \neq (H \cap K)\pi = M\rho^{-1} \longleftrightarrow M \xleftarrow{\nabla} L_{H} + L_{K} \\ \end{split}$$
Then, $\Gamma((H \cap K)\pi, \{w_{1}, w_{2}\}) = \Gamma(M\rho^{-1}, \{w_{1}, w_{2}\})$

1. Free-abelian-by-free grou	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection 000000000000000000000000000000000000



$$\mathbf{B} = \begin{bmatrix} 2\mathbf{a} - 3\mathbf{d} \\ \mathbf{a} - \mathbf{0} \end{bmatrix}$$
$$M = (L_H + L_K)\mathbf{B}^{-1}$$

We have that $(H \cap K)\pi = (L_H + L_K)\mathbf{B}^{-1}\rho^{-1} = M\rho^{-1}$, i.e.,

$$\mathbb{F}_{2} \geqslant H\pi \cap K\pi = \mathbb{F}_{\{w_{1},w_{2}\}} \xrightarrow{\rho} \mathbb{Z}^{2} \xrightarrow{\mathbf{B}} \mathbb{Z}^{2}$$

$$\stackrel{\nabla}{\rightarrow} \mathbb{Z}^{2} \xrightarrow{\nabla} \mathbb{Z}^{2} \xrightarrow{\nabla} \mathbb{Z}^{2}$$

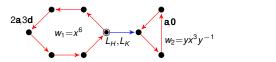
$$1 \neq (H \cap K)\pi = M\rho^{-1} \longleftrightarrow M \xleftarrow{\nabla} L_{H} + L_{K}$$

$$\text{Then, } \Gamma((H \cap K)\pi, \{w_{1}, w_{2}\}) = \Gamma(M\rho^{-1}, \{w_{1}, w_{2}\})$$

$$= Sch(M\rho^{-1}, \{w_{1}, w_{2}\})$$

(日)

1. Free-abelian-by-free gro	Stallings' automa	Vectored Stallings' automata	Membership 00	Intersection



$$\mathbf{B} = \begin{bmatrix} 2\mathbf{a} - 3\mathbf{d} \\ \mathbf{a} - \mathbf{0} \end{bmatrix}$$

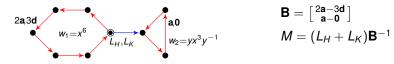
 $M = (L_H + L_K)\mathbf{B}^{-1}$

We have that $(H \cap K)\pi = (L_H + L_K)\mathbf{B}^{-1}\rho^{-1} = M\rho^{-1}$, i.e.,

$$\begin{split} \mathbb{F}_{2} \geqslant & H\pi \cap K\pi &= \mathbb{F}_{\{w_{1},w_{2}\}} \xrightarrow{\rho} \mathbb{Z}^{2} \xrightarrow{\mathbf{B}} \mathbb{Z}^{2} \\ & \bigtriangledown & \bigtriangledown & \bigtriangledown & \bigtriangledown & \bigtriangledown \\ & 1 \neq (H \cap K)\pi = & M\rho^{-1} \longleftrightarrow & M \xleftarrow{} & L_{H} + L_{K} \\ \text{Then, } \Gamma((H \cap K)\pi, \{w_{1}, w_{2}\}) &= \Gamma(M\rho^{-1}, \{w_{1}, w_{2}\}) \\ &= Sch \left(M\rho^{-1}, \{w_{1}, w_{2}\}\right) \\ &= Cay \left(\mathbb{F}_{\{w_{1}, w_{2}\}}/M\rho^{-1}, \{[w_{1}], [w_{2}]\}\right) \end{split}$$

▲□▶ ▲圖▶ ▲≣▶ ▲≣▶ = ● ● ●

1. Free-abelian-by-free groups	Stallings' automata 00000000000000000000	Membership 00	Intersection



We have that $(H \cap K)\pi = (L_H + L_K)\mathbf{B}^{-1}\rho^{-1} = M\rho^{-1}$, i.e.,

$$\begin{split} \mathbb{F}_{2} \geqslant & H\pi \cap K\pi &= \mathbb{F}_{\{w_{1},w_{2}\}} \xrightarrow{\rho} \mathbb{Z}^{2} \xrightarrow{\mathbf{B}} \mathbb{Z}^{2} \\ & \bigtriangledown & \bigtriangledown & \bigtriangledown & \bigtriangledown & \bigtriangledown \\ \mathbf{1} \neq (H \cap K)\pi &= & M\rho^{-1} \longleftrightarrow & M \xleftarrow{} & \downarrow \\ \mathsf{Then}, \ \mathsf{\Gamma}((H \cap K)\pi, \{w_{1}, w_{2}\}) &= \mathsf{\Gamma}(M\rho^{-1}, \{w_{1}, w_{2}\}) \\ &= & \mathsf{Sch}\left(M\rho^{-1}, \{w_{1}, w_{2}\}\right) \\ &= & \mathsf{Cay}\left(\mathbb{F}_{\{w_{1},w_{2}\}}/M\rho^{-1}, \{[w_{1}], [w_{2}]\}\right) \\ &= & \mathsf{Cay}\left(\mathbb{Z}^{2}/M, \{\mathbf{e}_{1}, \mathbf{e}_{2}\}\right) \end{split}$$

◆□ > ◆□ > ◆三 > ◆三 > ・三 ・ のへぐ

1. Free-abelian-by-free groups	Stallings' automata 0000000000000000000	Vectored Stallings' automata	Membership 00	Intersection

$$\mathbf{B} = \begin{bmatrix} 2\mathbf{a} - 3\mathbf{d} \\ \mathbf{a} - \mathbf{0} \end{bmatrix}$$

$$\mathbf{B} = \begin{bmatrix} 2\mathbf{a} - 3\mathbf{d} \\ \mathbf{a} - \mathbf{0} \end{bmatrix}$$

$$\mathbf{W}_1 = x^6$$

$$\mathbf{W}_2 = yx^3y^{-1}$$

$$\langle \mathbf{M} \rangle = \mathbf{M} = (L_H + L_K)\mathbf{B}^{-1}$$

We have that $(H \cap K)\pi = (L_H + L_K)\mathbf{B}^{-1}\rho^{-1} = M\rho^{-1}$, i.e.,

$$\begin{split} \mathbb{F}_{2} \geqslant & H\pi \cap K\pi &= \mathbb{F}_{\{w_{1},w_{2}\}} \xrightarrow{\rho} \mathbb{Z}^{2} \xrightarrow{\mathbf{B}} \mathbb{Z}^{2} \\ & \bigtriangledown & \bigtriangledown & \bigtriangledown & \bigtriangledown & \bigtriangledown \\ 1 \neq (H \cap K)\pi &= & M\rho^{-1} \longleftrightarrow & M \xleftarrow{} & L_{H} + L_{K} \\ \text{Then, } \Gamma((H \cap K)\pi, \{w_{1}, w_{2}\}) &= \Gamma(M\rho^{-1}, \{w_{1}, w_{2}\}) \\ &= & Sch\left(M\rho^{-1}, \{w_{1}, w_{2}\}\right) \\ &= & Cay\left(\mathbb{F}_{\{w_{1}, w_{2}\}}/M\rho^{-1}, \{[w_{1}], [w_{2}]\}\right) \\ &= & Cay\left(\mathbb{Z}^{2}/M, \{\mathbf{e}_{1}, \mathbf{e}_{2}\}\right) \end{split}$$

1. Free-abelian-by-free groups	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection

$$\mathbf{B} = \begin{bmatrix} 2\mathbf{a} - 3\mathbf{d} \\ \mathbf{a} - \mathbf{0} \end{bmatrix}$$

$$\mathbf{B} = \begin{bmatrix} 2\mathbf{a} - 3\mathbf{d} \\ \mathbf{a} - \mathbf{0} \end{bmatrix}$$

$$\mathbf{W}_1 = x^6$$

$$\mathbf{W}_2 = yx^3y^{-1}$$

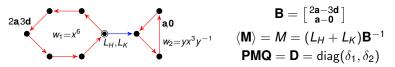
$$\langle \mathbf{M} \rangle = \mathbf{M} = (L_H + L_K)\mathbf{B}^{-1}$$

We have that $(H \cap K)\pi = (L_H + L_K)\mathbf{B}^{-1}\rho^{-1} = M\rho^{-1}$, i.e.,

$$\begin{split} \mathbb{F}_{2} \geqslant & H\pi \cap K\pi &= \mathbb{F}_{\{w_{1},w_{2}\}} \xrightarrow{\rho} \mathbb{Z}^{2} \xrightarrow{\mathbf{B}} \mathbb{Z}^{2} \\ & \bigtriangledown & \bigtriangledown & \bigtriangledown & \bigtriangledown & \bigtriangledown \\ 1 \neq (H \cap K)\pi &= & M\rho^{-1} \longleftrightarrow & M \xleftarrow{} & L_{H} + L_{K} \\ \text{Then, } \Gamma((H \cap K)\pi, \{w_{1}, w_{2}\}) &= \Gamma(M\rho^{-1}, \{w_{1}, w_{2}\}) \\ &= & Sch\left(M\rho^{-1}, \{w_{1}, w_{2}\}\right) \\ &= & Cay\left(\mathbb{F}_{\{w_{1}, w_{2}\}}/M\rho^{-1}, \{[w_{1}], [w_{2}]\}\right) \\ &= & Cay\left(\mathbb{Z}^{2}/\operatorname{row}(\mathbf{M}), \{\mathbf{e}_{1}, \mathbf{e}_{2}\}\right) \end{split}$$

▲□▶▲圖▶▲≣▶▲≣▶ = ● のへで

1. Free-abelian-by-free	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection

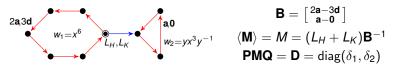


We have that $(H \cap K)\pi = (L_H + L_K)\mathbf{B}^{-1}\rho^{-1} = M\rho^{-1}$, i.e.,

$$\begin{split} \mathbb{F}_{2} \geqslant & H\pi \cap K\pi &= \mathbb{F}_{\{w_{1},w_{2}\}} \xrightarrow{\rho} \mathbb{Z}^{2} \xrightarrow{\mathbf{B}} \mathbb{Z}^{2} \\ \bigtriangledown & \bigtriangledown & \bigtriangledown & \bigtriangledown & \bigtriangledown & \bigtriangledown \\ \uparrow \neq (H \cap K)\pi &= M\rho^{-1} \xleftarrow{} M \xleftarrow{} L_{H} + L_{K} \\ \mathsf{Then}, \ \Gamma((H \cap K)\pi, \{w_{1}, w_{2}\}) &= \Gamma(M\rho^{-1}, \{w_{1}, w_{2}\}) \\ &= Sch \left(M\rho^{-1}, \{w_{1}, w_{2}\}\right) \\ &= Cay \left(\mathbb{F}_{\{w_{1}, w_{2}\}}/M\rho^{-1}, \{[w_{1}], [w_{2}]\}\right) \\ &= Cay \left(\mathbb{Z}^{2}/\operatorname{row}(\mathbf{M}), \{\mathbf{e}_{1}, \mathbf{e}_{2}\}\right) \\ &= Cay \left(\mathbb{Z}^{2}/\operatorname{row}(\mathbf{D}), \{\mathbf{e}_{1}\mathbf{Q}, \mathbf{e}_{2}\mathbf{Q}\}\right) \end{split}$$

◆□▶ ◆□▶ ▲□▶ ▲□▶ □ のQ@

1. Free-abelian-by-free	Stallings' automata	Vectored Stallings' automata	Membership 00	Intersection



We have that $(H \cap K)\pi = (L_H + L_K)\mathbf{B}^{-1}\rho^{-1} = M\rho^{-1}$, i.e.,

$$\begin{split} \mathbb{F}_{2} \geqslant & H\pi \cap K\pi &= \mathbb{F}_{\{w_{1},w_{2}\}} \xrightarrow{\rho} \mathbb{Z}^{2} \xrightarrow{\mathbf{B}} \mathbb{Z}^{2} \\ & \bigtriangledown & \bigtriangledown & \bigtriangledown & \bigtriangledown & \checkmark & \checkmark \\ 1 \neq (H \cap K)\pi &= & M\rho^{-1} \longleftrightarrow & M \xleftarrow{} & L_{H} + L_{K} \\ \text{Then, } \Gamma((H \cap K)\pi, \{w_{1}, w_{2}\}) &= \Gamma(M\rho^{-1}, \{w_{1}, w_{2}\}) \\ &= & Sch\left(M\rho^{-1}, \{w_{1}, w_{2}\}\right) \\ &= & Cay\left(\mathbb{F}_{\{w_{1},w_{2}\}}/M\rho^{-1}, \{[w_{1}], [w_{2}]\}\right) \\ &= & Cay\left(\mathbb{Z}^{2}/\operatorname{row}(\mathbf{M}), \{\mathbf{e}_{1}, \mathbf{e}_{2}\}\right) \\ &= & Cay\left(\mathbb{Z}^{2}/\operatorname{row}(\mathbf{D}), \{\mathbf{e}_{1}\mathbf{Q}, \mathbf{e}_{2}\mathbf{Q}\}\right) \\ &= & Cay\left(\mathbb{Z}/\delta_{1}\mathbb{Z} \oplus \mathbb{Z}/\delta_{2}\mathbb{Z}, \{\mathbf{e}_{1}\mathbf{Q}, \mathbf{e}_{2}\mathbf{Q}\}\right). \end{split}$$

・ロト・西ト・ヨト・ヨー うへぐ

Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

$$H = \langle t^{L_H}, \boldsymbol{x^3} \ t^{\mathbf{a}}, \boldsymbol{yx} \rangle, \ K = \langle t^{L_K}, \boldsymbol{x^2} \ t^{\mathbf{d}}, \boldsymbol{yxy^{-1}} \rangle \leqslant \mathbb{F}_2 \times \mathbb{Z}^2$$



Vectored Stallings' automata

Membership

Intersection

$$\begin{aligned} H &= \langle t^{L_H}, \mathbf{x}^3 \, t^{\mathbf{a}}, \mathbf{y} \mathbf{x} \rangle, \, K &= \langle t^{L_K}, \mathbf{x}^2 \, t^{\mathbf{d}}, \mathbf{y} \mathbf{x} \mathbf{y}^{-1} \rangle \leqslant \mathbb{F}_2 \times \mathbb{Z}^2 \\ \mathbf{Case 1:} \quad \mathbf{a} &= (1,0), \, \mathbf{d} = (0,1), \, L_H = \langle (0,6) \rangle, \, L_K &= \langle (3,-3) \rangle. \end{aligned}$$



Vectored Stallings' automata

Membership

Intersection

▲□▶ ▲□▶ ▲□▶ ▲□▶ = 三 のへで

$$\begin{array}{l} \mathcal{H} = \langle t^{\mathcal{L}_{\mathcal{H}}}, x^{3} \, t^{a}, yx \rangle, \, \mathcal{K} = \langle t^{\mathcal{L}_{\mathcal{K}}}, x^{2} \, t^{d}, yxy^{-1} \rangle \leqslant \mathbb{F}_{2} \times \mathbb{Z}^{2} \\ \textbf{Case 1:} \quad \textbf{a} = (1,0), \, \textbf{d} = (0,1), \, \mathcal{L}_{\mathcal{H}} = \langle (0,6) \rangle, \, \mathcal{L}_{\mathcal{K}} = \langle (3,-3) \rangle. \\ \textbf{Then, B} = \begin{bmatrix} 2 & -3 \\ 1 & 0 \end{bmatrix}, \, \textbf{M} = \begin{bmatrix} -2 & 4 \\ 1 & 1 \end{bmatrix}, \, \textbf{Q} = \begin{bmatrix} 1 & -1 \\ 0 & -1 \end{bmatrix}, \, \textbf{D} = \begin{bmatrix} 1 & 0 \\ 0 & 6 \end{bmatrix}. \end{array}$$

Vectored Stallings' automata

Membership 00 Intersection

▲□▶ ▲□▶ ▲□▶ ▲□▶ = 三 のへで

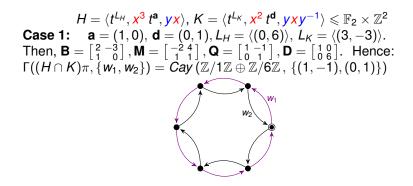
$$\begin{split} & H = \langle t^{L_H}, \boldsymbol{x}^3 \ t^{\mathbf{a}}, \boldsymbol{y} \boldsymbol{x} \rangle, \ K = \langle t^{L_K}, \boldsymbol{x}^2 \ t^{\mathbf{d}}, \boldsymbol{y} \boldsymbol{x} \boldsymbol{y}^{-1} \rangle \leqslant \mathbb{F}_2 \times \mathbb{Z}^2 \\ \textbf{Case 1:} \quad \mathbf{a} = (1,0), \ \mathbf{d} = (0,1), \\ & L_H = \langle (0,6) \rangle, \ L_K = \langle (3,-3) \rangle. \\ \textbf{Then, B} = \begin{bmatrix} 2 & -3 \\ 1 & 0 \end{bmatrix}, \ \mathbf{M} = \begin{bmatrix} -2 & 4 \\ 1 & 1 \end{bmatrix}, \ \mathbf{Q} = \begin{bmatrix} 1 & -1 \\ 0 & -1 \end{bmatrix}, \ \mathbf{D} = \begin{bmatrix} 1 & 0 \\ 0 & 6 \end{bmatrix}. \ \text{Hence:} \\ & \Gamma((H \cap K)\pi, \{w_1, w_2\}) = Cay \left(\mathbb{Z}/1\mathbb{Z} \oplus \mathbb{Z}/6\mathbb{Z}, \{(1,-1), (0,1)\} \right) \end{split}$$

Stallings' automata

Vectored Stallings' automata

Membership

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの



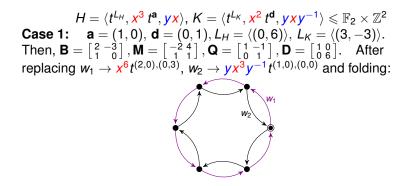
Stallings' automata

Vectored Stallings' automata

Membership

Intersection 000000000000000

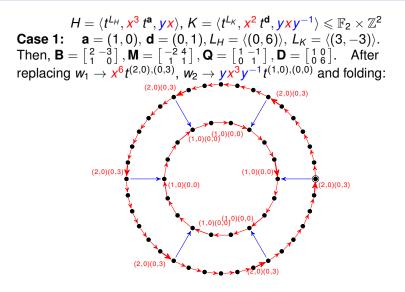
◆□▶ ◆□▶ ▲□▶ ▲□▶ ■ ののの



Vectored Stallings' automata

Membership

Intersection example: case 1

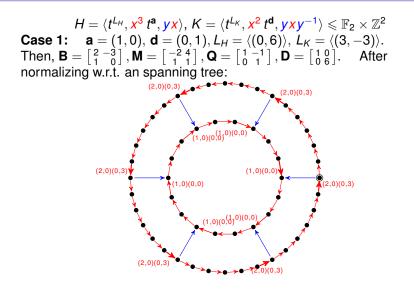


▲□▶▲圖▶★필▶★필▶ 重 の�?

Vectored Stallings' automata

Membership

Intersection example: case 1

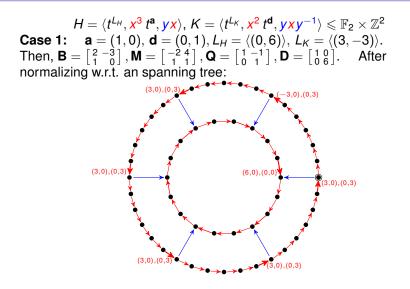


▲□▶▲□▶▲□▶▲□▶ ■ のへで

Vectored Stallings' automata

Membership

Intersection example: case 1

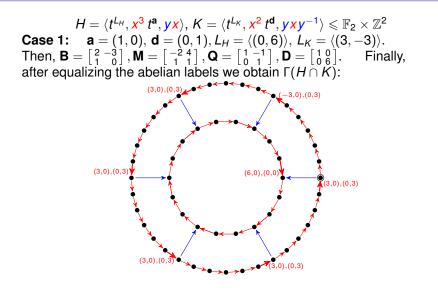


▲□▶▲圖▶▲≣▶▲≣▶ ■ のへで

Vectored Stallings' automata

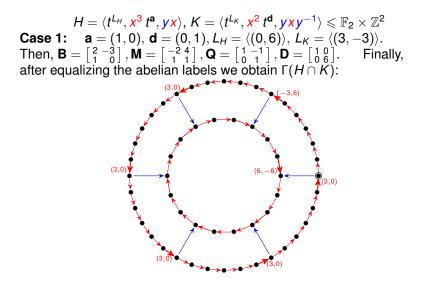
Membership

Intersection 000000000000000



Vectored Stallings' automata

Membership



Intersection example: case 1

Therefore, $H = \langle t^{(0,6)}, \mathbf{x}^3 t^{(1,0)}, \mathbf{y} \mathbf{x} \rangle \ K = \langle t^{(3,-3)}, \mathbf{x}^2 t^{(0,1)}, \mathbf{y} \mathbf{x} \mathbf{y}^{-1} \rangle$ and

$$H \cap K = \begin{pmatrix} x^{6}yx^{3}y^{-1}t^{(3,0)}, & x^{30}yx^{3}y^{-1}x^{-24}t^{(3,0)}, \\ x^{12}yx^{3}y^{-1}x^{-6}t^{(3,0)}, & x^{36}t^{(12,6)}, \\ x^{18}yx^{3}y^{-1}x^{-12}t^{(3,0)}, & yx^{18}y^{-1}t^{(6,-6)}, \\ x^{24}yx^{3}y^{-1}x^{-18}t^{(3,0)} & & \end{pmatrix}$$

Note, for example, that

$$H \cap K \ni \mathbf{x}^{36} t^{(12,6)} = \begin{cases} = \left(\mathbf{x}^{3} t^{(1,0)}\right)^{12} t^{(0,6)} \in H, \\ = \left(\mathbf{x}^{2} t^{(0,1)}\right)^{18} \left(t^{(3,-3)}\right)^{4} \in K. \end{cases}$$

And that $x^6 \in H\pi \cap K\pi$ but $x^6 \notin (H \cap K)\pi$ since

$$\begin{aligned} \mathbf{x}^{6}t^{(2,0)+\lambda(0,6)} \in \mathcal{H} \\ \mathbf{x}^{6}t^{(0,3)+\mu(3,-3)} \in \mathcal{K} \\ \text{but } \left((2,0) + \langle (0,6) \rangle \right) \cap \left((0,3) + \langle (3,-3) \rangle \right) = \emptyset. \end{aligned}$$

Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

$$H = \langle t^{L_H}, \boldsymbol{x^3} \ t^{\mathbf{a}}, \boldsymbol{yx} \rangle, \ \mathcal{K} = \langle t^{L_K}, \boldsymbol{x^2} \ t^{\mathbf{d}}, \boldsymbol{yxy^{-1}} \rangle \leqslant \mathbb{F}_2 \times \mathbb{Z}^2$$



Vectored Stallings' automata

Membership 00 Intersection

$$\begin{aligned} H &= \langle t^{L_H}, \mathbf{x}^3 \ t^{\mathbf{a}}, \mathbf{y} \mathbf{x} \rangle, \ K &= \langle t^{L_K}, \mathbf{x}^2 \ t^{\mathbf{d}}, \mathbf{y} \mathbf{x} \mathbf{y}^{-1} \rangle \leqslant \mathbb{F}_2 \times \mathbb{Z}^2 \\ \textbf{Case 2:} \quad \mathbf{a} &= (3,3), \ \mathbf{d} = (2,2), \\ L_H &= \langle (1,2) \rangle, \ L_K &= \langle (0,0) \rangle. \end{aligned}$$



Vectored Stallings' automata

Membership 00 Intersection

▲□▶ ▲□▶ ▲□▶ ▲□▶ = 三 のへで

$$\begin{aligned} H &= \langle t^{L_{H}}, \textbf{x}^{3} \ t^{a}, \textbf{yx} \rangle, \ K &= \langle t^{L_{K}}, \textbf{x}^{2} \ t^{d}, \textbf{yxy}^{-1} \rangle \leqslant \mathbb{F}_{2} \times \mathbb{Z}^{2} \\ \textbf{Case 2:} \quad \textbf{a} &= (3,3), \ \textbf{d} = (2,2), \\ L_{H} &= \langle (1,2) \rangle, \ L_{K} &= \langle (0,0) \rangle. \\ \textbf{Then}, \ \delta_{1} &= 1, \ \delta_{2} &= 0 \ \text{and so, } \ \Gamma(H \cap K) &= Cay \ (\mathbb{Z}, \{0,1\}). \end{aligned}$$

Vectored Stallings' automata

Membership

▲□▶ ▲□▶ ▲三▶ ▲三▶ 三三 のへで

$$\begin{aligned} H &= \langle t^{L_H}, \boldsymbol{x}^3 \, t^{\mathbf{a}}, \boldsymbol{y} \boldsymbol{x} \rangle, \, K &= \langle t^{L_K}, \boldsymbol{x}^2 \, t^{\mathbf{d}}, \boldsymbol{y} \boldsymbol{x} \boldsymbol{y}^{-1} \rangle \leqslant \mathbb{F}_2 \times \mathbb{Z}^2 \\ \textbf{Case 2:} \quad \mathbf{a} &= (3,3), \, \mathbf{d} = (2,2), L_H = \langle (1,2) \rangle, \, L_K = \langle (0,0) \rangle. \\ \text{Then, } \delta_1 &= 1, \, \delta_2 = 0 \text{ and so, } \Gamma(H \cap K) = Cay \, (\mathbb{Z}, \{0,1\}). \end{aligned}$$



Vectored Stallings' automata

Membership

Intersection

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

Intersection example: case 2

$$H = \langle t^{L_H}, \mathbf{x}^3 t^{\mathbf{a}}, \mathbf{y} \mathbf{x} \rangle, K = \langle t^{L_K}, \mathbf{x}^2 t^{\mathbf{d}}, \mathbf{y} \mathbf{x} \mathbf{y}^{-1} \rangle \leq \mathbb{F}_2 \times \mathbb{Z}^2$$

Case 2: $\mathbf{a} = (3,3), \mathbf{d} = (2,2), L_H = \langle (1,2) \rangle, L_K = \langle (0,0) \rangle.$
Then, $\delta_1 = 1, \delta_2 = 0$ and so, $\Gamma(H \cap K) = Cay(\mathbb{Z}, \{0,1\}).$



After replacing, folding, normalizing, and equalizing, we obtain $\Gamma(H \cap K)$:

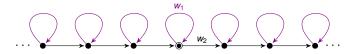
Vectored Stallings' automata

Membership

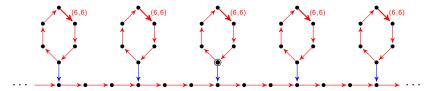
Intersection

Intersection example: case 2

$$\begin{aligned} H &= \langle t^{L_H}, \boldsymbol{x}^3 \ t^{\mathbf{a}}, \boldsymbol{y} \boldsymbol{x} \rangle, \ K &= \langle t^{L_K}, \boldsymbol{x}^2 \ t^{\mathbf{d}}, \boldsymbol{y} \boldsymbol{x} \boldsymbol{y}^{-1} \rangle \leqslant \mathbb{F}_2 \times \mathbb{Z}^2 \\ \textbf{Case 2:} \quad \mathbf{a} &= (3,3), \ \mathbf{d} = (2,2), \\ L_H &= \langle (1,2) \rangle, \ L_K &= \langle (0,0) \rangle. \\ \textbf{Then}, \ \delta_1 &= 1, \ \delta_2 &= 0 \ \text{and so, } \ \Gamma(H \cap K) &= Cay \ (\mathbb{Z}, \{0,1\}). \end{aligned}$$



After replacing, folding, normalizing, and equalizing, we obtain $\Gamma(H \cap K)$:



▲□▶▲圖▶▲≣▶▲≣▶ ≣ のQ@

Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

$$H = \langle t^{L_H}, \boldsymbol{x^3} \ t^{\mathbf{a}}, \boldsymbol{yx} \rangle, \ K = \langle t^{L_K}, \boldsymbol{x^2} \ t^{\mathbf{d}}, \boldsymbol{yxy^{-1}} \rangle \leqslant \mathbb{F}_2 \times \mathbb{Z}^2$$

Vectored Stallings' automata

Membership 00 Intersection

$$\begin{array}{l} \mathcal{H} = \langle t^{\mathcal{L}_{\mathcal{H}}}, \textbf{\textit{x}}^3 \ t^{\textbf{a}}, \textbf{\textit{yx}} \rangle, \ \mathcal{K} = \langle t^{\mathcal{L}_{\mathcal{K}}}, \textbf{\textit{x}}^2 \ t^{\textbf{d}}, \textbf{\textit{yxy}}^{-1} \rangle \leqslant \mathbb{F}_2 \times \mathbb{Z}^2 \\ \textbf{Case 3:} \quad \textbf{a} = (3,3), \ \textbf{d} = (2,2), \ \mathcal{L}_{\mathcal{H}} = \langle (2,2) \rangle, \ \mathcal{L}_{\mathcal{K}} = \langle (0,0) \rangle. \end{array}$$



Vectored Stallings' automata

Membership 00 Intersection

▲□▶ ▲□▶ ▲ 三▶ ▲ 三▶ - 三 - のへぐ

$$\begin{aligned} H &= \langle t^{L_H}, \boldsymbol{x}^3 \ t^{\mathbf{a}}, \boldsymbol{y} \boldsymbol{x} \rangle, \ K &= \langle t^{L_K}, \boldsymbol{x}^2 \ t^{\mathbf{d}}, \boldsymbol{y} \boldsymbol{x} \boldsymbol{y}^{-1} \rangle \leqslant \mathbb{F}_2 \times \mathbb{Z}^2 \\ \textbf{Case 3:} \quad \mathbf{a} &= (3,3), \ \mathbf{d} = (2,2), \ L_H &= \langle (2,2) \rangle, \ L_K &= \langle (0,0) \rangle. \\ \textbf{Then}, \ \delta_1 &= 1, \ \delta_2 &= 2 \ \text{and so,} \ \Gamma(H \cap K) &= Cay \left(\mathbb{Z}/2\mathbb{Z}, \{0,1\} \right). \end{aligned}$$

Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

▲□▶ ▲□▶ ▲三▶ ▲三▶ 三三 のへで

$$\begin{aligned} H &= \langle t^{\mathcal{L}_{\mathcal{H}}}, \boldsymbol{x}^{3} t^{\mathbf{a}}, \boldsymbol{y} \boldsymbol{x} \rangle, \, \boldsymbol{K} &= \langle t^{\mathcal{L}_{\mathcal{K}}}, \boldsymbol{x}^{2} t^{\mathbf{d}}, \boldsymbol{y} \boldsymbol{x} \boldsymbol{y}^{-1} \rangle \leqslant \mathbb{F}_{2} \times \mathbb{Z}^{2} \\ \textbf{Case 3:} \quad \mathbf{a} &= (3,3), \, \mathbf{d} = (2,2), \, \mathcal{L}_{\mathcal{H}} = \langle (2,2) \rangle, \, \mathcal{L}_{\mathcal{K}} &= \langle (0,0) \rangle. \\ \textbf{Then}, \, \delta_{1} &= 1, \, \delta_{2} = 2 \text{ and so, } \Gamma(\mathcal{H} \cap \mathcal{K}) = Cay \left(\mathbb{Z}/2\mathbb{Z}, \{0,1\} \right). \end{aligned}$$



Stallings' automata

Vectored Stallings' automata

Membership

Intersection

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のQで

Intersection example: case 3

$$\begin{aligned} H &= \langle t^{L_{H}}, \boldsymbol{x}^{3} t^{\mathbf{a}}, \boldsymbol{y} \boldsymbol{x} \rangle, \, K &= \langle t^{L_{K}}, \boldsymbol{x}^{2} t^{\mathbf{d}}, \boldsymbol{y} \boldsymbol{x} \boldsymbol{y}^{-1} \rangle \leqslant \mathbb{F}_{2} \times \mathbb{Z}^{2} \\ \textbf{Case 3:} \quad \mathbf{a} &= (3,3), \, \mathbf{d} = (2,2), \, L_{H} = \langle (2,2) \rangle, \, L_{K} &= \langle (0,0) \rangle. \\ \textbf{Then}, \, \delta_{1} &= 1, \, \delta_{2} &= 2 \text{ and so, } \Gamma(H \cap K) &= Cay \left(\mathbb{Z}/2\mathbb{Z}, \{0,1\} \right). \end{aligned}$$



After replacing, folding, normalizing, and equalizing, we obtain $\Gamma(H \cap K)$:

Vectored Stallings' automata

Membership

Intersection

Intersection example: case 3

$$\begin{aligned} H &= \langle t^{\mathcal{L}_{\mathcal{H}}}, \boldsymbol{x}^{3} t^{\mathbf{a}}, \boldsymbol{y} \boldsymbol{x} \rangle, \, K &= \langle t^{\mathcal{L}_{\mathcal{K}}}, \boldsymbol{x}^{2} t^{\mathbf{d}}, \boldsymbol{y} \boldsymbol{x} \boldsymbol{y}^{-1} \rangle \leqslant \mathbb{F}_{2} \times \mathbb{Z}^{2} \\ \textbf{Case 3:} \quad \mathbf{a} &= (3,3), \, \mathbf{d} = (2,2), \, \mathcal{L}_{\mathcal{H}} = \langle (2,2) \rangle, \, \mathcal{L}_{\mathcal{K}} = \langle (0,0) \rangle. \\ \text{Then,} \, \delta_{1} &= 1, \, \delta_{2} = 2 \text{ and so, } \Gamma(H \cap K) = Cay \left(\mathbb{Z}/2\mathbb{Z}, \{0,1\} \right). \end{aligned}$$



After replacing, folding, normalizing, and equalizing, we obtain $\Gamma(H \cap K)$:



Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

$$H = \langle t^{L_H}, \boldsymbol{x^3} \ t^{\mathbf{a}}, \boldsymbol{yx} \rangle, \ \mathcal{K} = \langle t^{L_{\mathcal{K}}}, \boldsymbol{x^2} \ t^{\mathbf{d}}, \boldsymbol{yxy^{-1}} \rangle \leqslant \mathbb{F}_2 \times \mathbb{Z}^2$$



Vectored Stallings' automata

Membership 00 ▲□▶▲□▶▲□▶▲□▶ □ のQ@

Intersection example: case 4

$$\begin{split} H &= \langle t^{L_H}, \boldsymbol{x^3} \ t^{\mathbf{a}}, \boldsymbol{yx} \rangle, \ K &= \langle t^{L_K}, \boldsymbol{x^2} \ t^{\mathbf{d}}, \boldsymbol{yxy^{-1}} \rangle \leqslant \mathbb{F}_2 \times \mathbb{Z}^2 \\ \textbf{Case 4:} \quad \mathbf{a} &= (6, 6), \ \mathbf{d} = (4, 4) \in \mathbb{Z}^2, \ L_H = \langle (6p, 6p) \rangle, \ L_K &= \langle (0, 0) \rangle, \\ \text{for some } p \in \mathbb{Z}, \ p \neq 0. \end{split}$$

Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

▲□▶▲□▶▲□▶▲□▶ □ のQ@

Intersection example: case 4

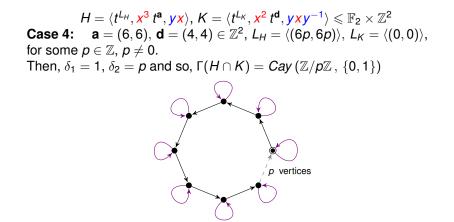
 $\begin{aligned} H &= \langle t^{L_H}, \boldsymbol{x}^3 \ t^{\mathbf{a}}, \boldsymbol{y} \boldsymbol{x} \rangle, \ K &= \langle t^{L_K}, \boldsymbol{x}^2 \ t^{\mathbf{d}}, \boldsymbol{y} \boldsymbol{x} \boldsymbol{y}^{-1} \rangle \leqslant \mathbb{F}_2 \times \mathbb{Z}^2 \\ \textbf{Case 4:} \quad \mathbf{a} &= (6, 6), \ \mathbf{d} = (4, 4) \in \mathbb{Z}^2, \ L_H &= \langle (6p, 6p) \rangle, \ L_K &= \langle (0, 0) \rangle, \\ \text{for some } p \in \mathbb{Z}, \ p \neq 0. \\ \text{Then, } \delta_1 &= 1, \ \delta_2 &= p \text{ and so, } \Gamma(H \cap K) = Cay \left(\mathbb{Z}/p\mathbb{Z}, \ \{0, 1\} \right) \end{aligned}$

Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

▲□▶▲□▶▲□▶▲□▶ □ のQ@



 1. Free-abelian-by-free groups
 Stallings' automata
 Vectored Stallings' automata
 Membership

 000000
 000000
 00000
 00000
 00

Intersection

▲□▶▲□▶▲□▶▲□▶ □ のQ@

Intersection example: case 4

After replacing, folding, normalizing, and equalizing, we obtain $\Gamma(H \cap K)$:

. Free-abelian-by-free groups Stalli

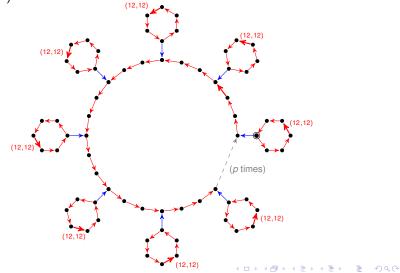
Stallings' automata

Vectored Stallings' automata

Membership 00 Intersection

Intersection example: case 4

After replacing, folding, normalizing, and equalizing, we obtain $\Gamma(H \cap K)$:



1. Free-abelian-by-free groups Stallings' automata Vectored Stallings' automata Membership Intersection

Intersection example: case 4

Therefore,
$$H_p = \langle t^{(6p,6p)}, x^3 t^{(6,6)}, yx \rangle$$
, $K = \langle x^2 t^{(4,4)}, yx y^{-1} \rangle$ and

$$H \cap K = \left\langle \begin{array}{c} (yx^{-3}y^{-1})^{-1}x^{6}(yx^{-3}y^{-1})t^{(12,12)} \\ (yx^{-3}y^{-1})^{-2}x^{6}(yx^{-3}y^{-1})^{2}t^{(12,12)} \\ \vdots \\ (yx^{-3}y^{-1})^{-(p-1)}x^{6}(yx^{-3}y^{-1})^{p-1}t^{(12,12)} \\ yx^{3p}y^{-1} \end{array} \right\rangle$$

Note that $r(H_p) = 3$, r(K) = 2, but

$$r(H_p \cap K) = p + 1.$$

So, no Hanna Neumann type inequality $\tilde{r}(H \cap K) \leq C \cdot \tilde{r}(H) \cdot \tilde{r}(K)$ is possible in these groups.

▲ロト▲母ト▲目ト▲目ト 目 のへぐ

 Free-abelian-by-free groups 	Stallings' automata	Vectored Stallings' automata	Membership	Intersection
000000				0000000000000000

THANKS

▲□▶▲圖▶▲≣▶▲≣▶ ≣ の�?